

Tools to Ascend the Ladder of Causation

Causal reasoning

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Causal hierarchy

- Do people who exercise more tend to have lower rates of heart disease?

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- Can we predict who is at higher risk of developing diabetes using BIG DATA?

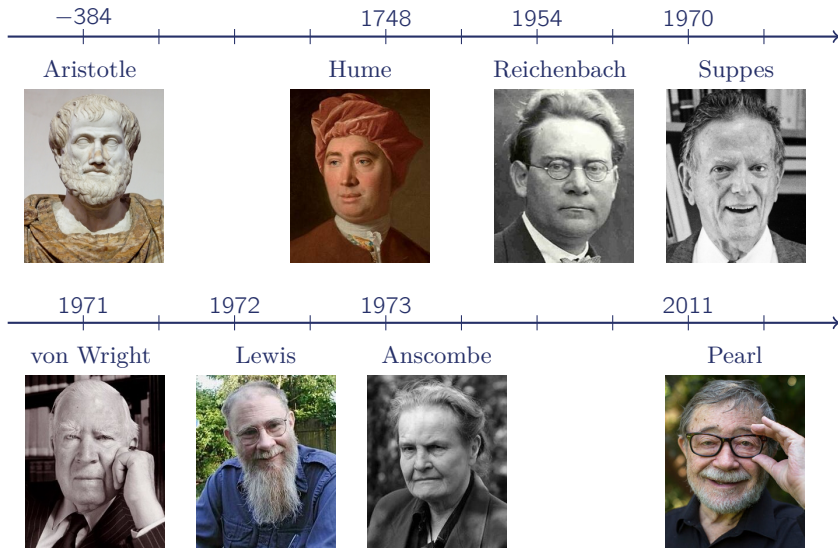
- Do people who exercise more tend to have lower rates of heart disease?
- Can we predict who is at higher risk of developing diabetes using BIG DATA?
- Does exercising reduce cholesterol?

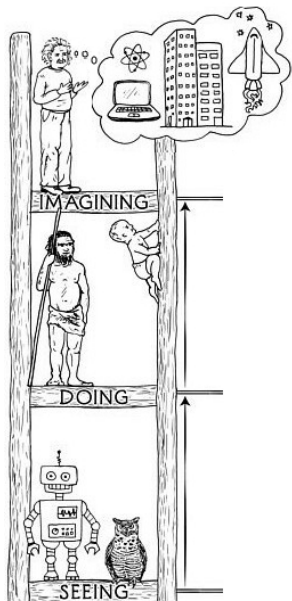
- Do people who exercise more tend to have lower rates of heart disease?
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- Does exercising reduce cholesterol?
- What happens to headache intensity if we prescribe aspirin?

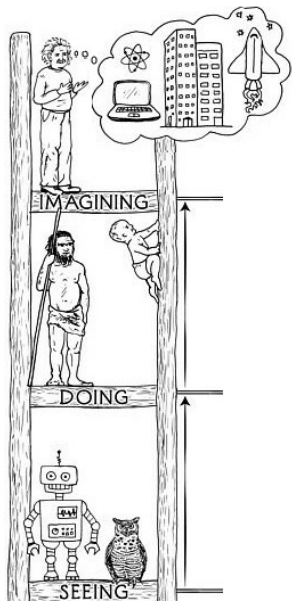
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- Would COVID-19 outcomes in France have changed with a different policy?
- Was it the aspirin that stopped by headache?

A history of attempts ...

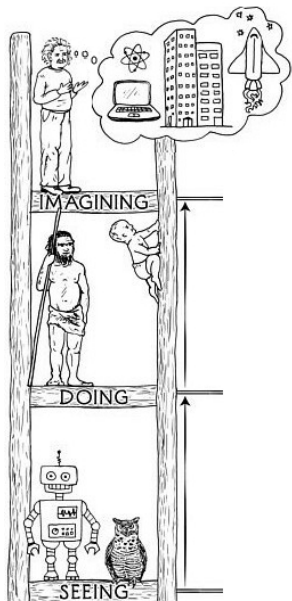






■ Associations

- ▶ Questions : What if I see ...?
- ▶ Do people who exercise more tend to have lower rates of heart disease?
- ▶ Can we predict who is at higher risk of developing diabetes using BIG DATA?

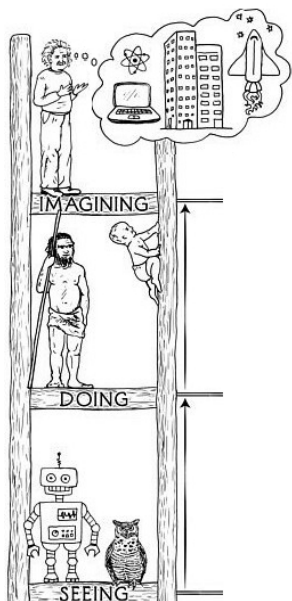


■ Interventions

- ▶ Questions: What if I do ...? How?
- ▶ Does exercising reduce cholesterol?
- ▶ What happens to headache intensity if we prescribe aspirin?

■ Associations

- ▶ Questions : What if I see ...?
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■ Counterfactuals

- ▶ Questions: What if I had done ...? Why?
- ▶ Would COVID-19 outcomes in France have changed with a different policy?
- ▶ Was it the aspirin that stopped by headache?

■ Interventions

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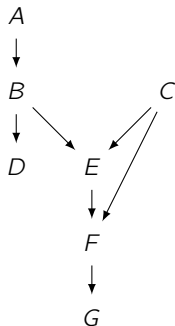
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Associations

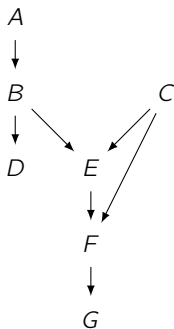
- Sets: $\mathbb{A} = \{X, Y, Z\}$
- Statistical independence: $\perp\!\!\!\perp_P$
- Statistical dependence: $\not\perp\!\!\!\perp_P$

A graph $\mathcal{G} = (\mathbb{V}, \mathbb{E})$ is said to be a **directed acyclic graph (DAG)** if

- \mathbb{V} is the set of nodes (usually each node corresponds to a random variable),
- \mathbb{E} is the set of edges,
- $\forall (X, Y) \in \mathbb{E}$,
there is an arrow pointing from X to Y ,
- there are no directed cycle in \mathcal{G} .

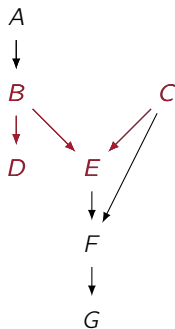


Consider the following DAG $\mathcal{G} = (\mathcal{V}, \mathbb{E})$:



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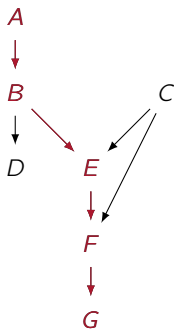
Path: $D \leftarrow B \rightarrow E \leftarrow C$



Consider the following DAG $\mathcal{G} = (\mathcal{V}, \mathbb{E})$:

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Directed path: $A \rightarrow B \rightarrow E \rightarrow F \rightarrow G$

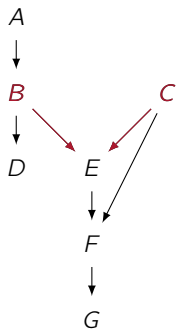


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Parents: $Pa(E) = \{B, C\}$



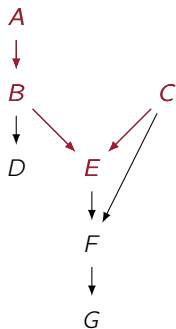
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Ancestors: $An(E) = \{A, B, C, E\}$



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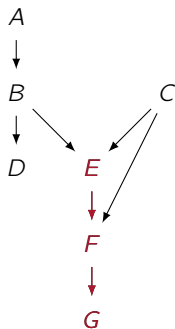
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Descendants: $De(E) = \{E, F, G\}$



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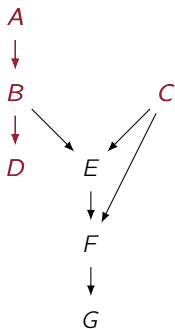
Directed path: $A \rightarrow B \rightarrow E \rightarrow F \rightarrow G$

Parents: $Pa(E) = \{B, C\}$

Ancestors: $An(E) = \{A, B, C, E\}$

Descendants: $De(E) = \{E, F, G\}$

Non-descendants: $Nd(E) = \{A, B, C, D\}$



Consider the following DAG $\mathcal{G} = (\mathcal{V}, \mathbb{E})$:

Path: $D \leftarrow B \rightarrow E \leftarrow C$

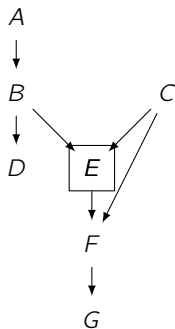
Directed path: $A \rightarrow B \rightarrow E \rightarrow F \rightarrow G$

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Descendants: $De(E) = \{E, F, G\}$

Non-descendants: $Nd(E) = \{A, B, C, D\}$



Conditioning: represented by a square

```
#Load the pyCIPHOD package
from pyciphod.graphs import DirectedAcyclicGraph
#Define the Directed graph
g = DirectedAcyclicGraph()
g.add_vertices(["A", "B", "C"])
g.add_directed_edge('B', 'A')
g.add_directed_edge('B', 'C')
g.remove_directed_edge("A", "C")
#Print nodes and edges
print(g.get_vertices())
print(g.get_directed_edges())
#Print parents and children
print(g.get_parents("A"))
print(g.get_children("B"))
```

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$$\forall X \in \mathbb{V}, X \perp\!\!\!\perp_P Nd(X) \mid Pa(X) \text{ (Markov condition)}$$

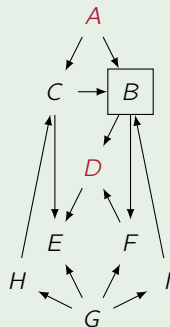
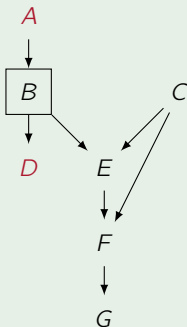
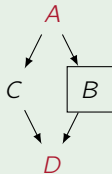
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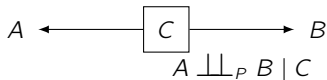
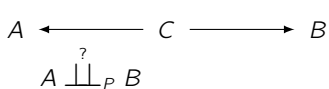
A DAG $\mathcal{G} = (\mathbb{V}, \mathbb{E})$ is a **Bayesian network** if there exists a joint distribution $P(\mathbb{V})$ that is compatible with \mathcal{G} .

Example

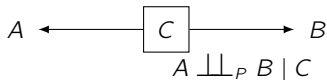
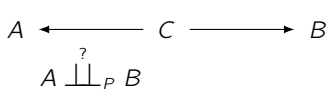
$$A \perp\!\!\!\perp_P D \mid B$$



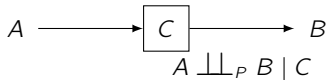
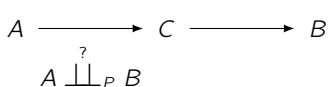
Fork: contains a common parent



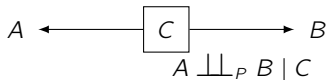
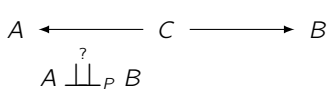
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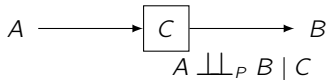
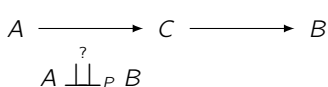
Chain: directed path



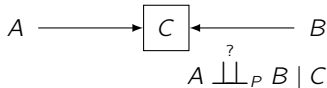
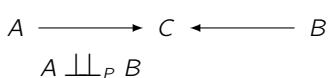
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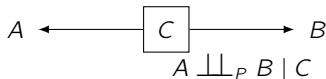
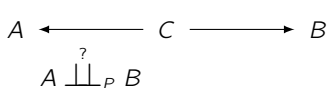
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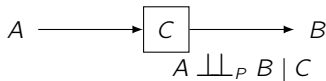
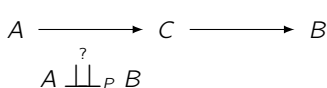
Collider : contains a common child



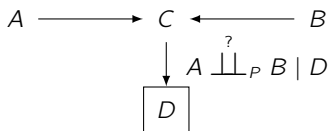
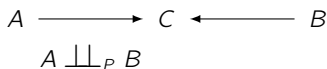
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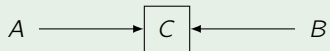
Chain: directed path



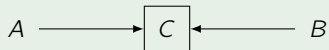
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Example



Example

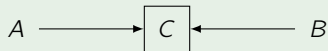


$$A = \begin{cases} \text{Mother carrier} \\ \text{Mother not carrier} \end{cases}$$

$$B = \begin{cases} \text{Father carrier} \\ \text{Father not carrier} \end{cases}$$

$$C = (A \text{ or } B) = \begin{cases} \text{Child carrier} \\ \text{Child not carrier} \end{cases}$$

Example



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$$C = (A \text{ or } B) = \begin{cases} \text{Child carrier} \\ \text{Child not carrier} \end{cases}$$

If $C = \text{Child carrier} \implies$

$$\begin{cases} \text{If } A = \text{Mother not carrier then } B = \text{Father carrier} \\ \text{If } B = \text{Father not carrier then } A = \text{Mother carrier} \end{cases}$$

Example



Example

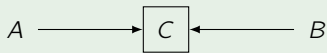


$$A, B \sim U(-1, 1)$$

$$U_c \sim N(0, \frac{1}{2})$$

$$C = 2AB + U_c$$

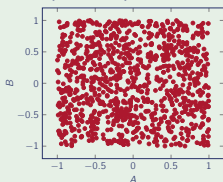
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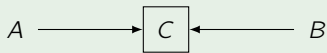
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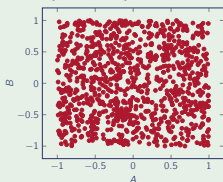


$$\text{Corr}(A; B) = 0.002$$

Example



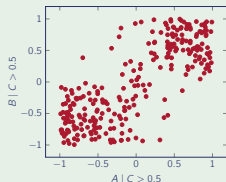
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$$\text{Corr}(A; B \mid C > 0.5) = 0.8$$

A path is said to be **blocked** by a set of nodes $\mathbb{Z} \in \mathbb{V}$ if:

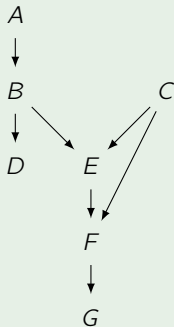
- it contains a chain $A \rightarrow B \rightarrow C$ or a fork $A \leftarrow B \rightarrow C$ and $B \in \mathbb{Z}$; or
- it contains a collider $A \rightarrow B \leftarrow C$ such that no descendant of B is in \mathbb{Z} .

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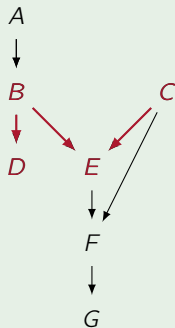
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A path that is not blocked is **active**.

Example

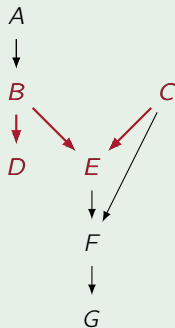


Example



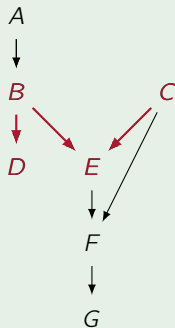
Is the path $\langle D, B, E, C \rangle$ blocked?

Example



Is the path $\langle D, B, E, C \rangle$ blocked? Yes

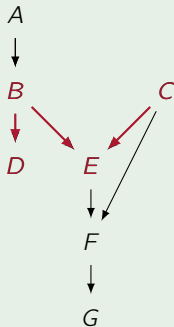
Example



Is the path $\langle D, B, E, C \rangle$ blocked? **Yes**

Is the path $\langle D, B, E, C \rangle$ blocked by E ?

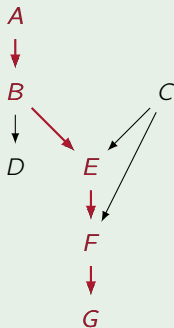
Example



Is the path $\langle D, B, E, C \rangle$ blocked? **Yes**

Is the path $\langle D, B, E, C \rangle$ blocked by E ? **No**

Example

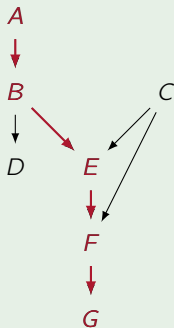


Is the path $\langle D, B, E, C \rangle$ blocked? **Yes**

Is the path $\langle D, B, E, C \rangle$ blocked by E ? **No**

Is the path $\langle A, B, E, F, G \rangle$ blocked?

Example

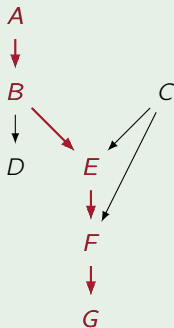


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Example



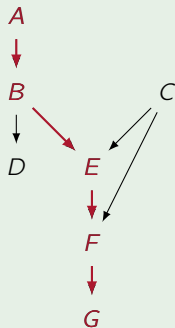
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Given disjoint sets $X, Y, Z \subseteq V$, we say that X and Y are **d-separated** by Z if every path between a node in X and a node in Y is blocked by Z and we write $X \perp\!\!\!\perp_G Y \mid Z$.

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If one path is not blocked, we say that X and Y are **d-connected** given Z and we write $X \not\perp\!\!\!\perp_G Y \mid Z$.

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Theorem

$$X \perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \Rightarrow \forall P \text{ compatible with } \mathcal{G}, X \perp\!\!\!\perp_P Y \mid Z$$

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If one path is not blocked, we say that X and Y are **d-connected** given Z and we write $X \not\perp\!\!\!\perp_{\mathcal{G}} Y \mid Z$.

Theorem

$X \perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \Rightarrow \forall P$ compatible with $\mathcal{G}, X \perp\!\!\!\perp_P Y \mid Z$
 but $X \not\perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \not\Rightarrow \forall P$ compatible with $\mathcal{G}, X \not\perp\!\!\!\perp_P Y \mid Z$

Given disjoint sets $X, Y, Z \subseteq V$, we say that X and Y are **d-separated** by Z if every path between a node in X and a node in Y is blocked by Z and we write $X \perp\!\!\!\perp_{\mathcal{G}} Y \mid Z$.

If one path is not blocked, we say that X and Y are **d-connected** given Z and we write $X \not\perp\!\!\!\perp_{\mathcal{G}} Y \mid Z$.

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 but $X \not\perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \not\Rightarrow \forall P$ compatible with $\mathcal{G}, X \not\perp\!\!\!\perp_P Y \mid Z$ instead
 $X \not\perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \Rightarrow \exists P$ compatible with $\mathcal{G}, X \not\perp\!\!\!\perp_P Y \mid Z$

Given disjoint sets $X, Y, Z \subseteq \mathcal{V}$, we say that X and Y are **d-separated** by Z if every path between a node in X and a node in Y is blocked by Z and we write $X \perp\!\!\!\perp_{\mathcal{G}} Y \mid Z$.

If one path is not blocked, we say that X and Y are **d-connected** given Z and we write $X \not\perp\!\!\!\perp_{\mathcal{G}} Y \mid Z$.

Theorem

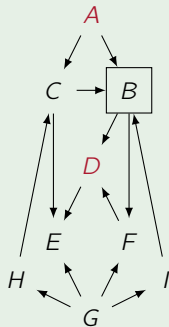
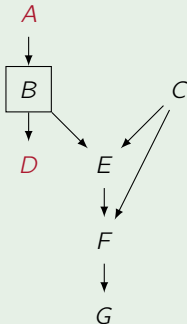
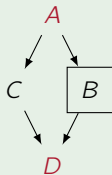
$X \perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \Rightarrow \forall P$ compatible with $\mathcal{G}, X \perp\!\!\!\perp_P Y \mid Z$
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$X \perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \Rightarrow X \perp\!\!\!\perp_P Y \mid Z$

$X \not\perp\!\!\!\perp_{\mathcal{G}} Y \mid Z \Rightarrow X \overset{?}{\perp\!\!\!\perp}_P Y \mid Z$

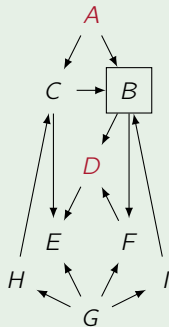
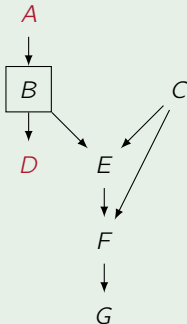
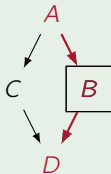
Example

Is $A \perp\!\!\!\perp_P D \mid B$?



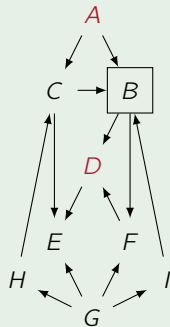
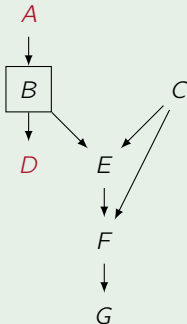
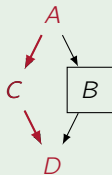
Example

Is $A \perp\!\!\!\perp_D D \mid B$?



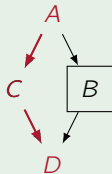
Example

Is $A \perp\!\!\!\perp D \mid B$?



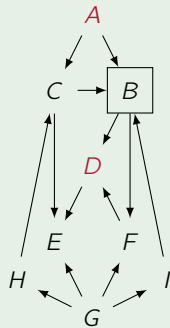
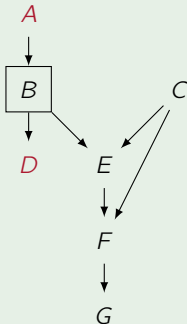
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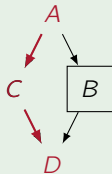
$\langle A, C, D \rangle$ is not blocked

$\Rightarrow A \perp\!\!\!\perp_P D \mid B$



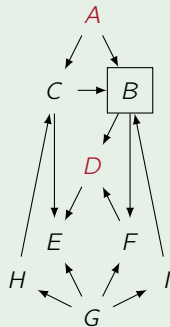
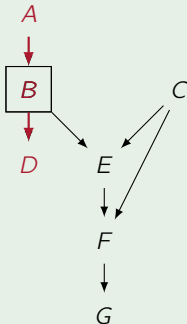
Example

Is $A \perp\!\!\!\perp_P D \mid B$?



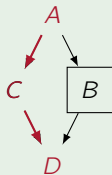
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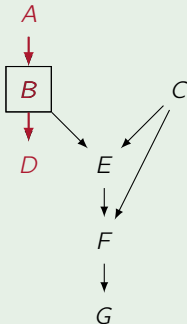
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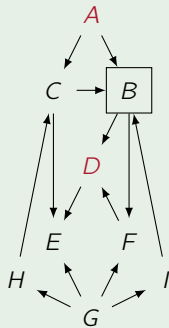


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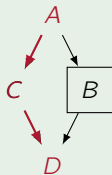


All paths are blocked
 $\Rightarrow A \perp\!\!\!\perp_P D \mid B$



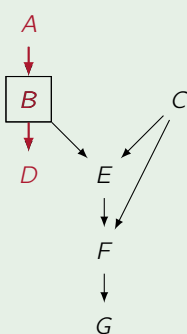
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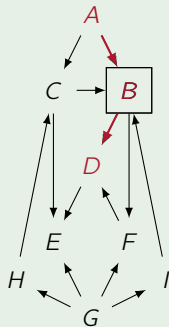
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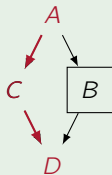
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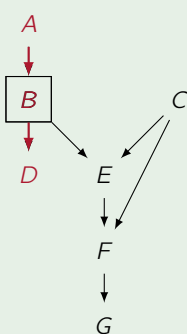
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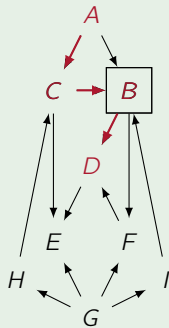


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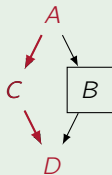


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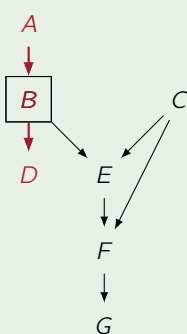
Example

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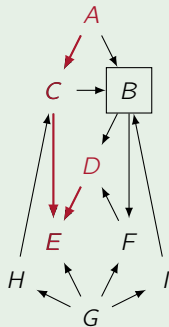


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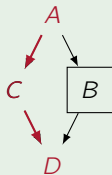


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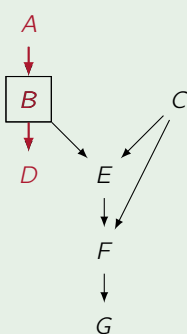
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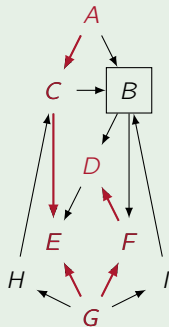


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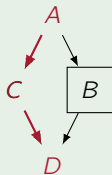


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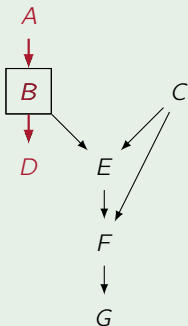
Example

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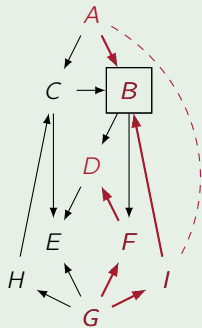


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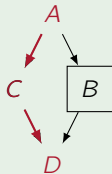


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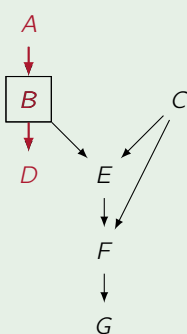
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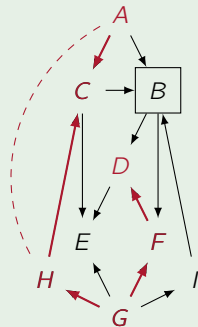


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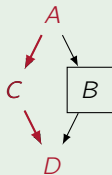


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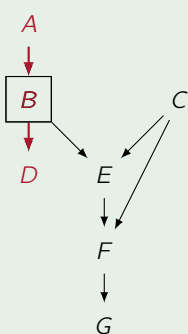
Example

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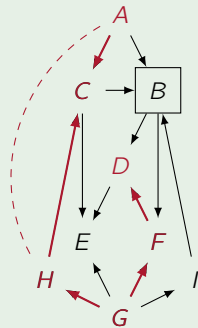
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All paths are blocked

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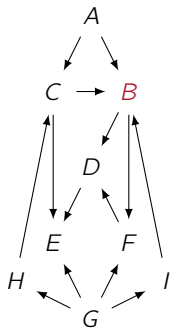


$\langle A, B, I, G, F, D \rangle$ is not blocked

$\Rightarrow A \perp\!\!\!\perp_P D \mid B$

```
#Load the pyCIPHOD package
from pyciphod.graphs import DirectedAcyclicGraph
from pyciphod.separation import d_separated
#Define the DAG
g = DirectedAcyclicGraph()
g.add_vertices(["A", "B", "C"])
g.add_directed_edge('B', 'A')
g.add_directed_edge('B', 'C')
#Check if B d-separates A and C
ds = g.d_separated(["A"], ["C"], ["B"])
print(ds)
```

What are the relevant variables for predicting B ?



3

Interventions

The causal effect of A on Y

$$= \mathbb{E}(Y \mid do(A = a)) - \mathbb{E}(Y \mid do(A = a')).$$

The operator $do()$ represents interventions.

The causal effect of A on Y

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Population



The causal effect of A on Y

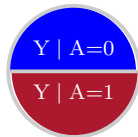
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Population



Sub-
populations



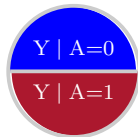
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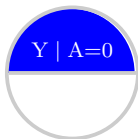
Population



Sub-
populations

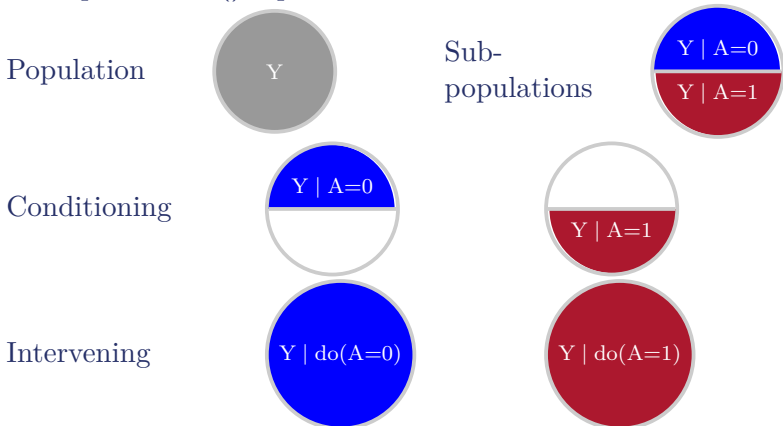


Conditioning

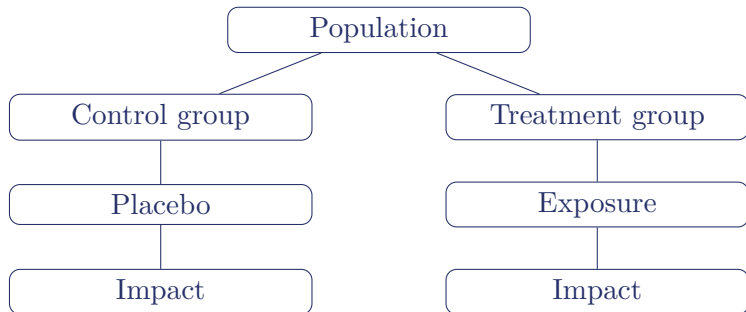


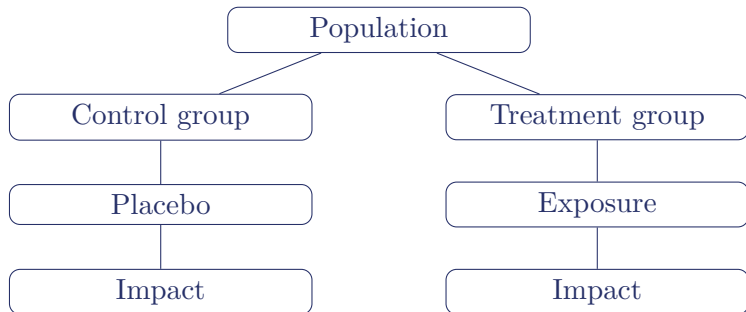
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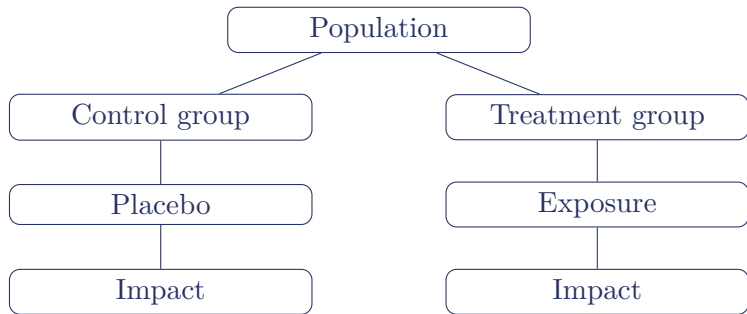
Gold standard: Randomized controlled trials





Limitations:

- Unethical
- Infeasible
- Costly

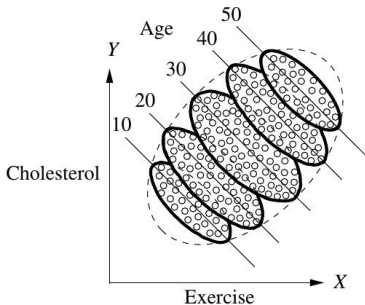


Limitations:

- Unethical
- Infeasible
- Costly

⇒ Sometimes we have to rely on observational studies.

In a study, we measure weekly exercise and cholesterol levels across different age groups. What is the causal effect of exercise on cholesterol?



Estimating causal effects from observational data necessarily requires strong assumptions.

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Two main frameworks

Potential outcomes

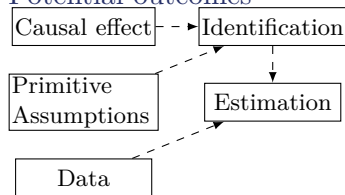
Structural causal models

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Two main frameworks

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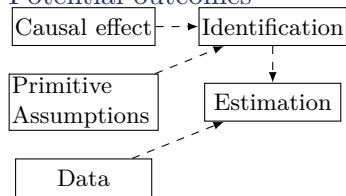
Structural causal models



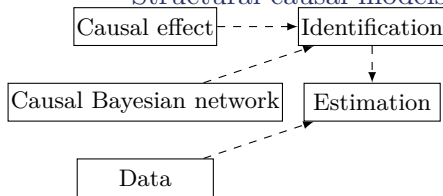
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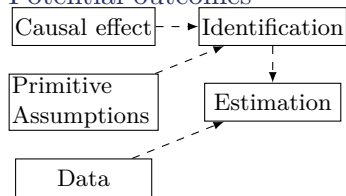
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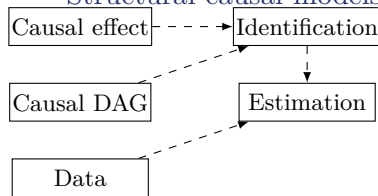
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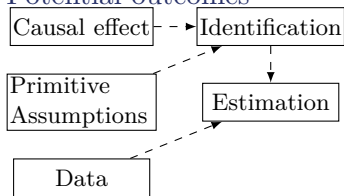
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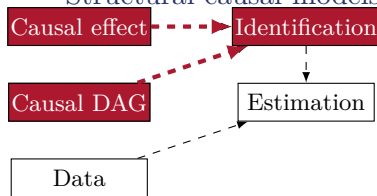
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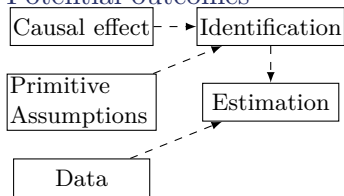
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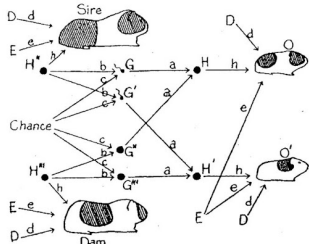
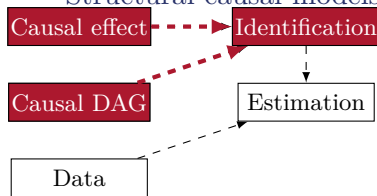
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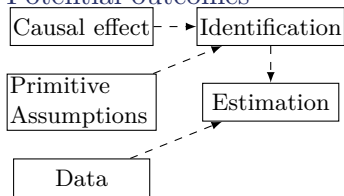


Sewall Wright

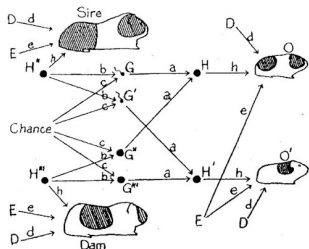
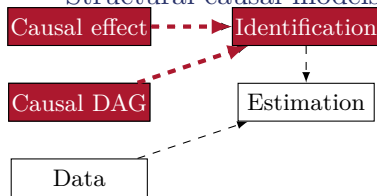
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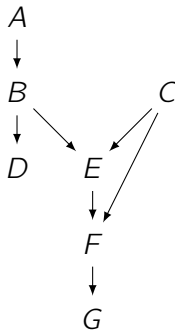
Sewall Wright



Judea Pearl

A causal DAG $\mathcal{G} = (\mathbb{V}, \mathbb{E})$ is a bayesian network where

- \mathbb{E} represents direct causal relations between variables in \mathbb{V} .

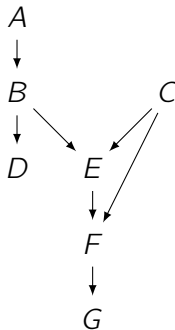


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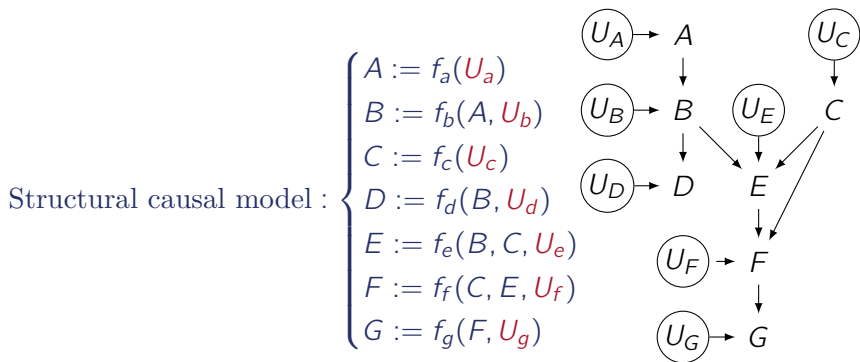
Structural causal model :

$$\left\{ \begin{array}{l} A := f_a(U_a) \\ B := f_b(A, U_b) \\ C := f_c(U_c) \\ D := f_d(B, U_d) \\ E := f_e(B, C, U_e) \\ F := f_f(C, E, U_f) \\ G := f_g(F, U_g) \end{array} \right.$$



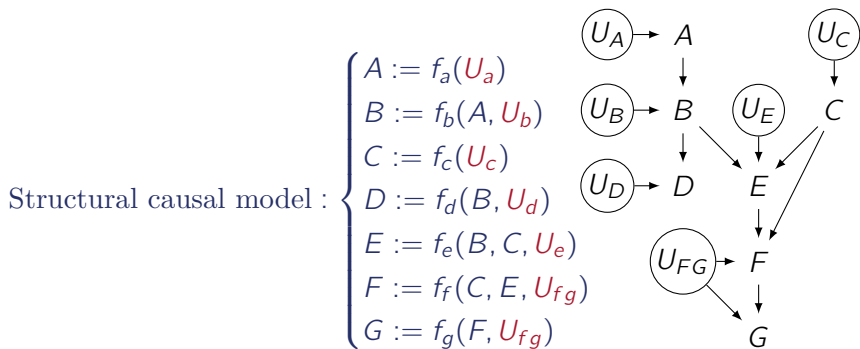
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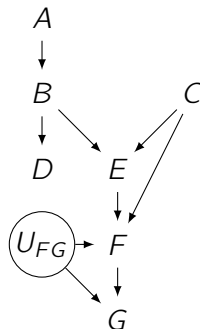


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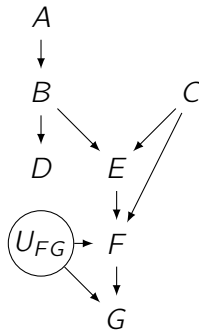


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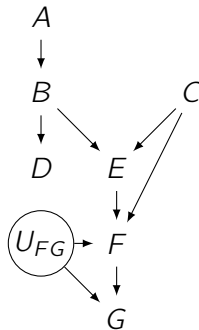


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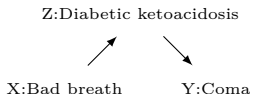
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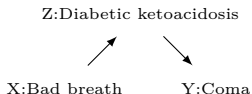
In a structural causal model, the intervention $\text{do}(F = f)$ is defined by replacing the structural equation of F with $F := f$, leaving all other equations unchanged.

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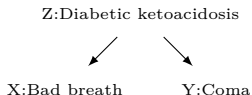
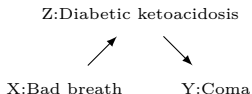


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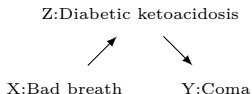
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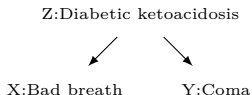


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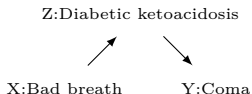


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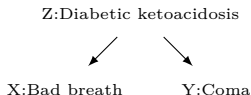
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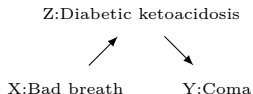
Oracle for conditional
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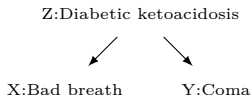
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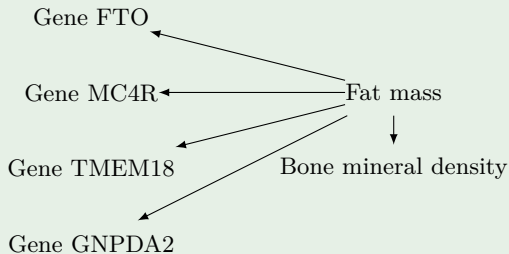


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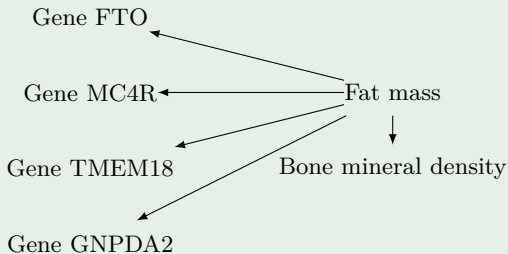
It is impossible to determine, without additional assumptions, which of the two DAGs is causal based solely on the observed distribution!

Example



Is this DAG causal?

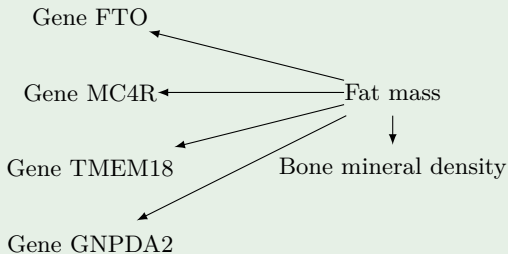
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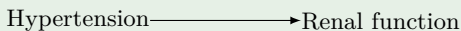
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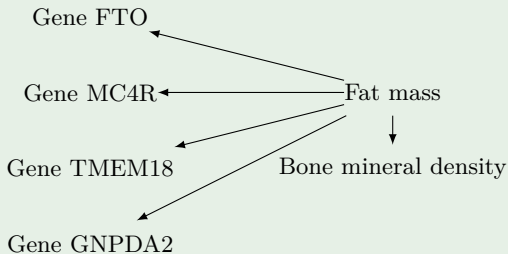


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- Think carefully about the orientation
- When you are not sure if you need to add or not an edge (for example $Z \rightarrow A$) to the graph, **ADD IT!** (as long as you keep the graph acyclic)

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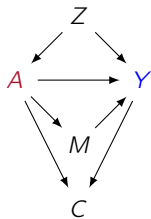
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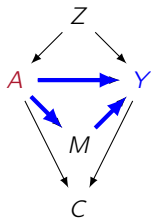


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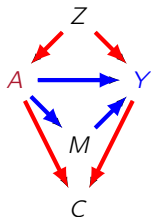


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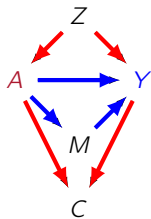


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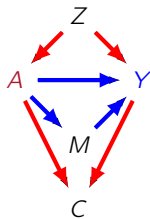
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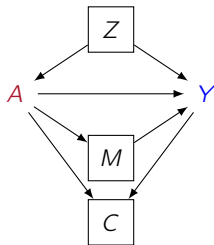


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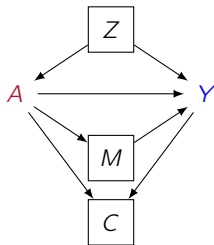
In what follows, we will simplify the notation by using $P(y \mid do(a))$ instead of $P(Y = y \mid do(A = a))$.

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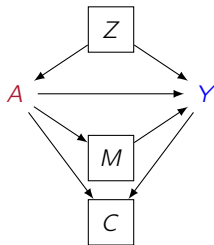


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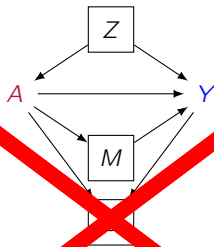


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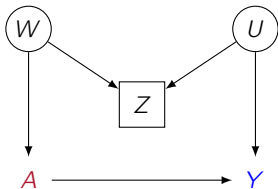
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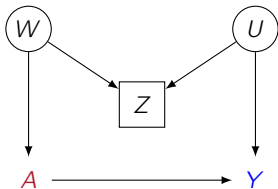
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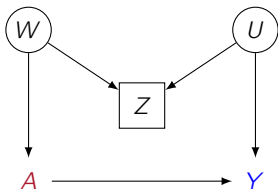


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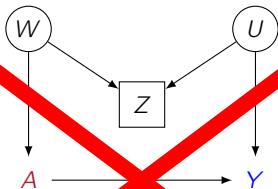


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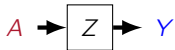
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This criterion can be extended to a set A and a set Y .

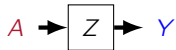
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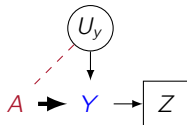
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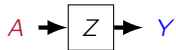
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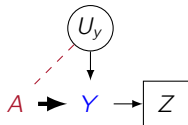
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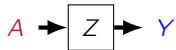


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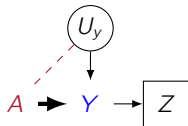
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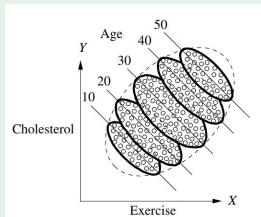
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This one is the "obvious".

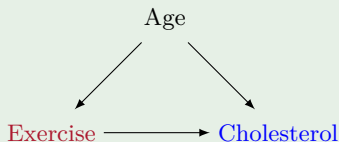
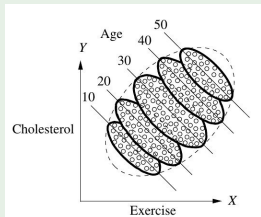
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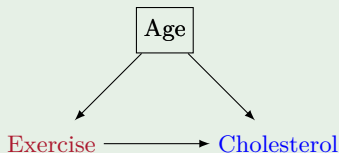
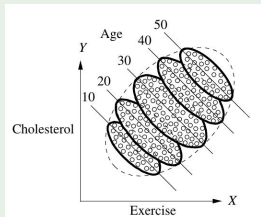
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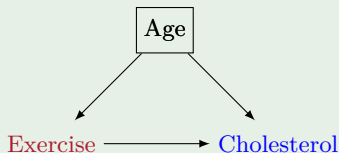
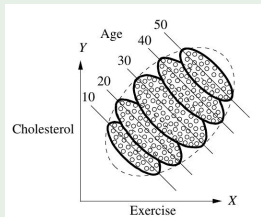
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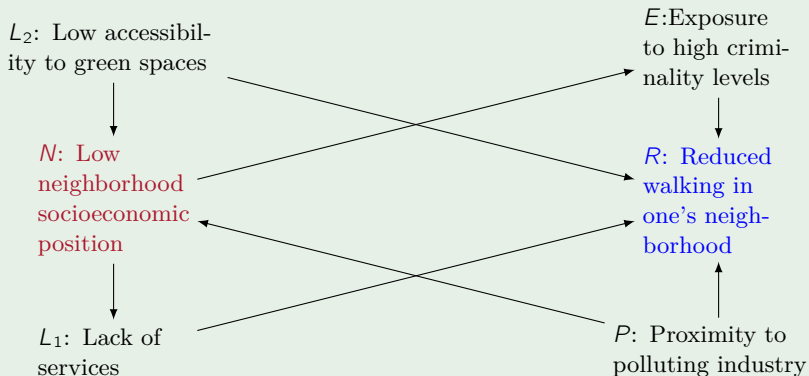
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In this study, we aim to estimate the effect of the neighborhood's socioeconomic status (N) on the reduction of walking within the neighborhood (R), $P(r \mid do(n))$?

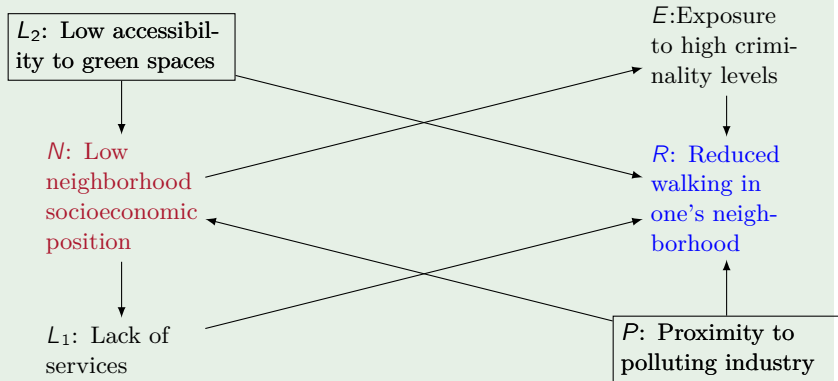
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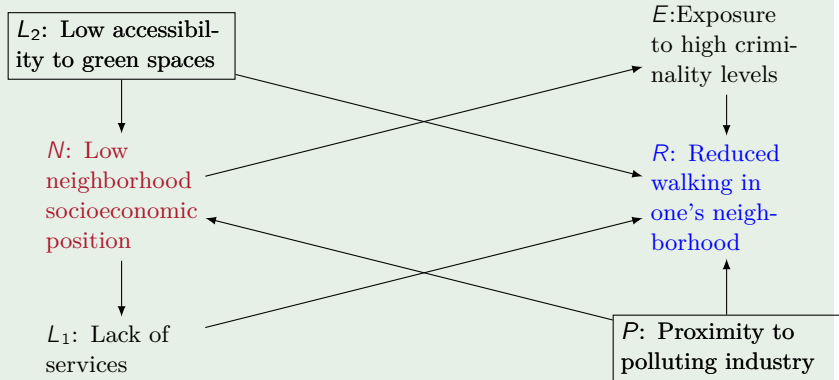
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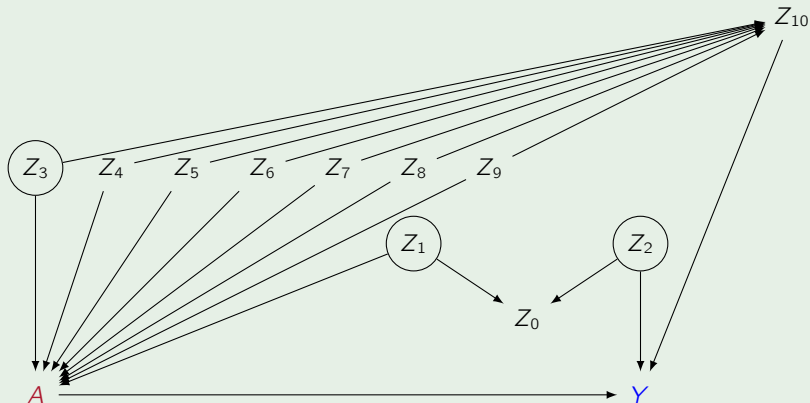
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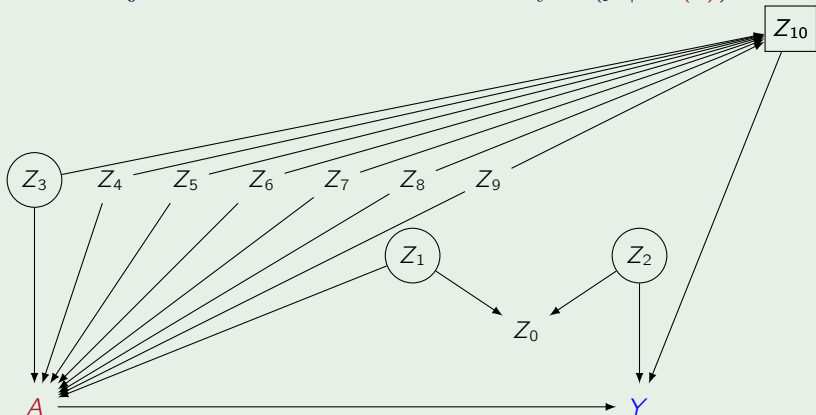
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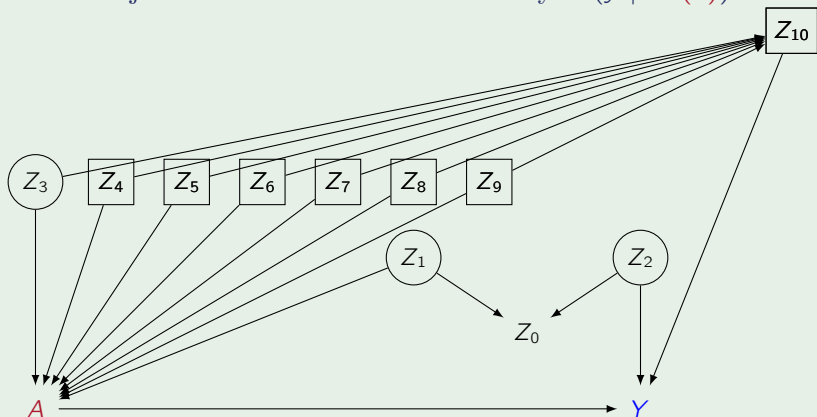
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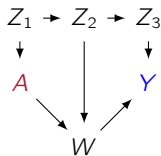


Many sets of variables can satisfy the back-door criterion:

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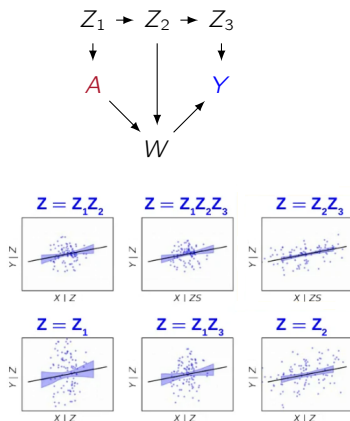
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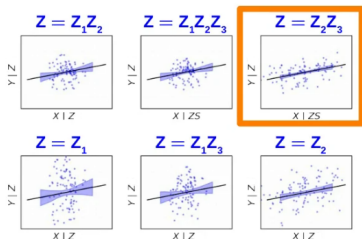
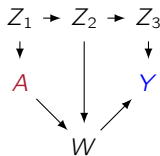
Many sets of variables can satisfy the back-door criterion:

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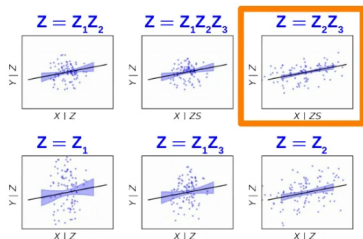
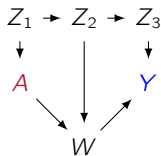
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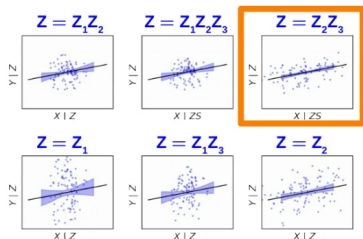
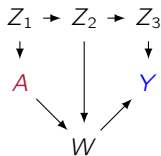


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A set Z satisfying the back-door criterion relative to (A, Y) is **optimal** if:

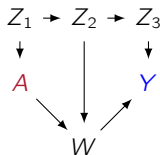
- Z includes all parents of Y that are not mediators between A and Y , and



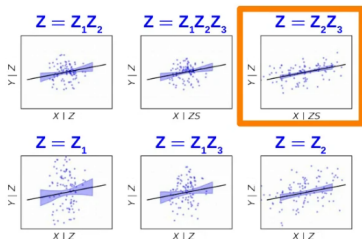
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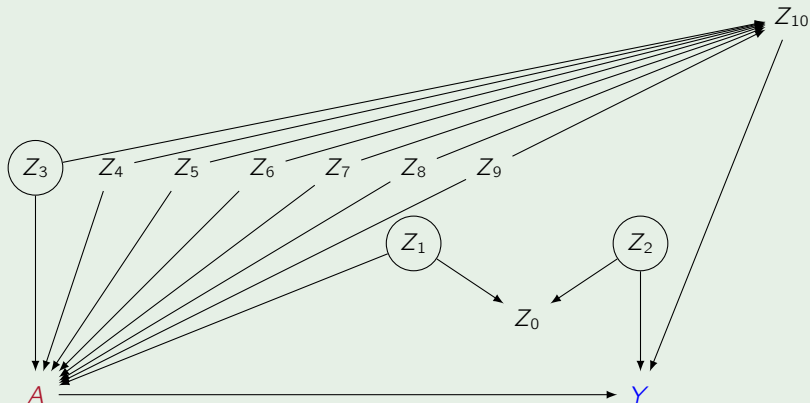


- Z includes all parents of Y that are not mediators between A and Y , and
- Z includes all parents of any mediator between A and Y , that are not themselves mediators between A and Y .



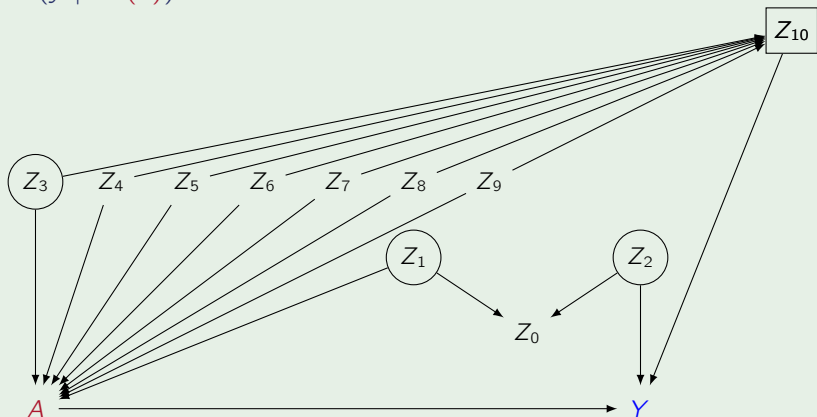
Example

What is the optimal adjustment set that allow us to identify $\Pr(y | do(a))$?



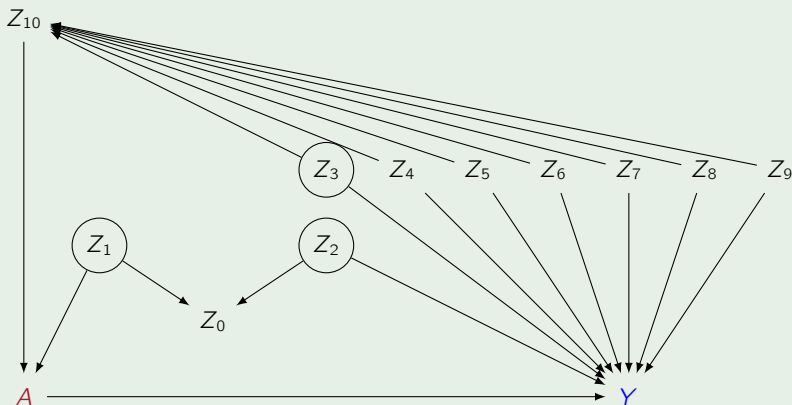
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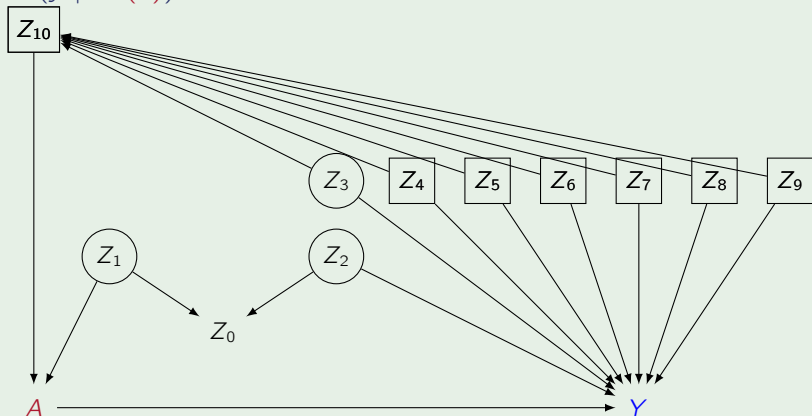
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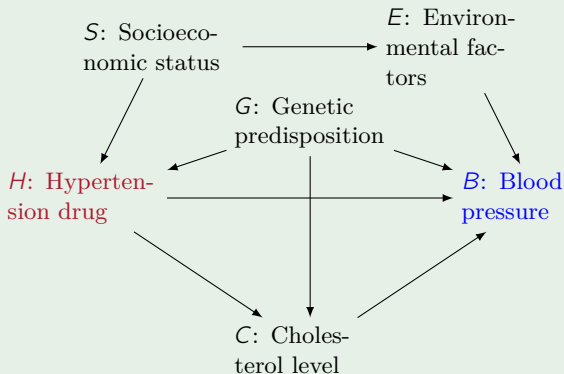


Example

How to optimally estimate the effect of new hypertension drug (H) on blood pressure (B) $P(b \mid do(h))$?

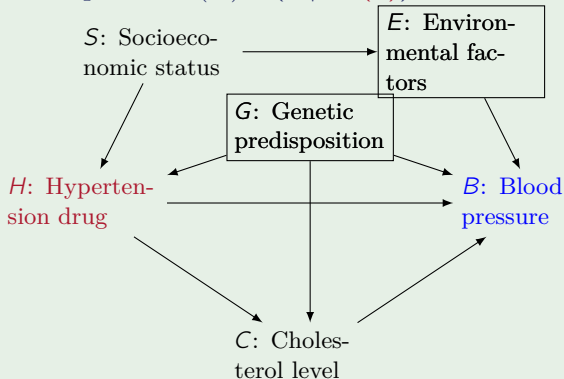
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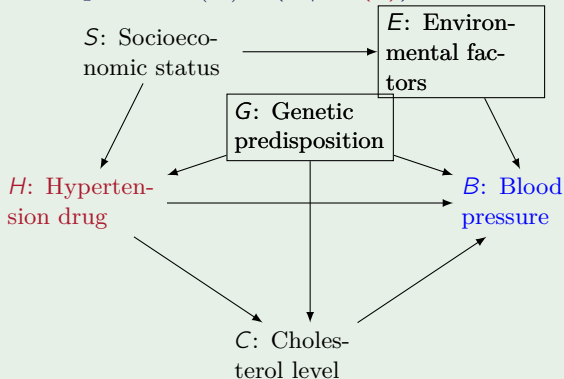
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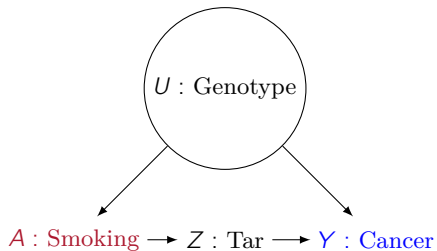
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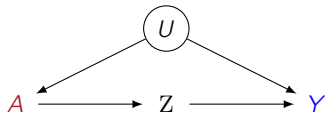


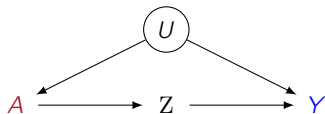
$$P(b | do(h)) = \sum_{g,e} P(b|h, g, e)P(g, e)$$

The back-door criterion is not complete:

- If no set satisfies the back-door criterion for $P(y \mid do(x))$, this does not necessarily mean that $P(y \mid do(x))$ is not identifiable.

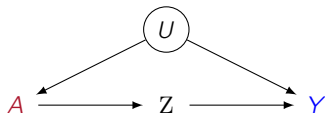




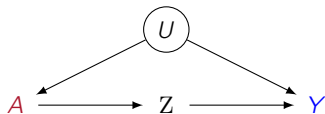


- $P(z | do(a)) = P(z | a)$

(No non-causal path)

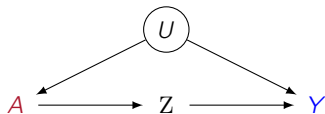


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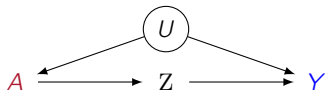
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■ $P(z | do(a)) = P(z | a)$ (No non-causal path)

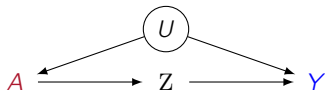
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$$\begin{aligned}
 P(y | do(a)) &= \sum_z P(y | do(z))P(z | do(a)) \\
 &= \sum_z P(z | a) \sum_{a'} P(y | z, a')P(a')
 \end{aligned}$$



A set of measured variables Z satisfies the front-door criterion relative to an ordered pair of variables (A, Y) in causal DAG \mathcal{G} if:

- Z intercepts all causal paths from A to Y ;
- There is no non-causal path from A to Z ;
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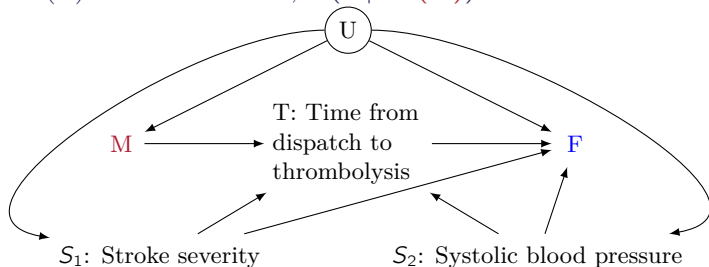
Theorem

If Z satisfies the front-door criterion relative to (A, Y) and if $P(a, z) > 0$, then the causal effect of A on Y is identifiable and is given by

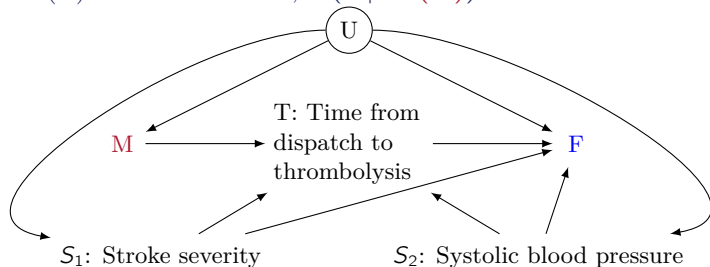
$$P(y \mid do(a)) = \sum_z P(z \mid a) \sum_{a'} P(y \mid a', z) P(a').$$

In this study, Piccininni et al. were interested in estimating the effect of Mobile Stroke Unit dispatch (M) on functional outcomes (F). In other words, $P(f \mid do(m))$?

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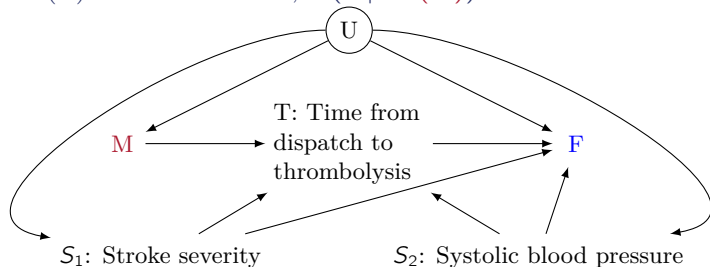


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Best paper in Epidemiology in 2024!

The front-door criterion is not complete:

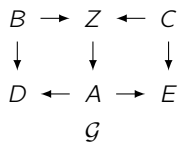
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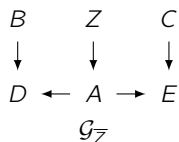
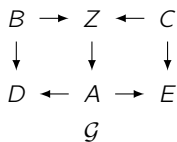
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The combination of the back-door and the front-door criteria is also not complete.

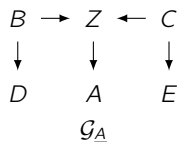
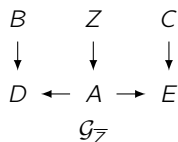
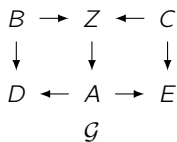
Mutilated graphs:



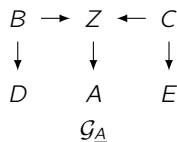
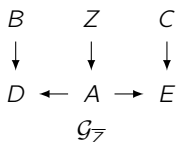
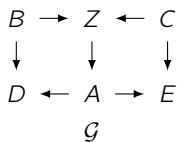
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The do-calculus:

Rule 1: $P(y \mid \text{do}(z), \alpha, w) = P(y \mid \text{do}(z), w)$

if $(Y \perp\!\!\!\perp A \mid Z, W)_{\mathcal{G}_{\bar{Z}}}$

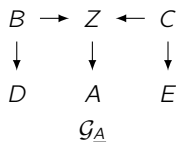
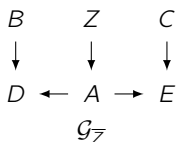
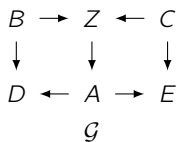
Rule 2: $P(y \mid \text{do}(z, \alpha), w) = P(y \mid \text{do}(z), \alpha, w)$

if $(Y \perp\!\!\!\perp A \mid Z, W)_{\mathcal{G}_{\bar{Z}A}}$

Rule 3: $P(y \mid \text{do}(z, \alpha), w) = P(y \mid \text{do}(z), w)$

if $(Y \perp\!\!\!\perp A \mid Z, W)_{\mathcal{G}_{\bar{Z}A(W)}}$

Mutilated graphs:



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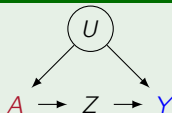
- Rule 1:** $P(y \mid \text{do}(z), a, w) = P(y \mid \text{do}(z), w)$ if $(Y \perp\!\!\!\perp A \mid Z, W)_{\mathcal{G}_{\bar{Z}}}$
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- Rule 3:** $P(y \mid \text{do}(z, a), w) = P(y \mid \text{do}(z), w)$ if $(Y \perp\!\!\!\perp A \mid Z, W)_{\mathcal{G}_{\bar{Z}, \bar{A}(w)}}$

Theorem

$P(y \mid \text{do}(a))$ is identifiable if and only if there exists a finite sequence of transformations, each conforming to either one of the Rules 1-3 or some standard probability manipulations, that reduces $P(y \mid \text{do}(a))$ into a do-free formula.

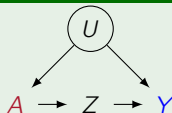
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Example



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Example



$$\begin{aligned}
 &P(y \mid \text{do}(a)) \\
 &= \sum_z P(y \mid \text{do}(a), z) P(z \mid \text{do}(a)) \\
 &= \sum_z P(y \mid a, z) P(z \mid \text{do}(a)) \quad (\text{Rule 2}) \\
 &= \sum_z P(y \mid a, z) P(z) \quad (\text{Rule 3})
 \end{aligned}$$

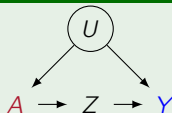
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Causal Inference



$$\begin{aligned}
 &P(y \mid \text{do}(a)) \\
 &= \sum_z P(y \mid \text{do}(a), z) P(z \mid \text{do}(a)) \\
 &= \sum_z P(y \mid \text{do}(a), \text{do}(z)) P(z \mid a) \quad (\text{Rule 2}) \times 2 \\
 &= \sum_z P(y \mid \text{do}(z)) P(z \mid a) \quad (\text{Rule 3}) \\
 &= \sum_{z, a'} P(y \mid \text{do}(z), a') P(a' \mid \text{do}(z)) P(z \mid a) \\
 &= \sum_{z, a'} P(y \mid z, a') P(a' \mid \text{do}(z)) P(z \mid a) \quad (\text{Rule 2})
 \end{aligned}$$

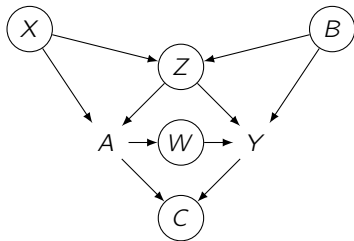
Interventions

```

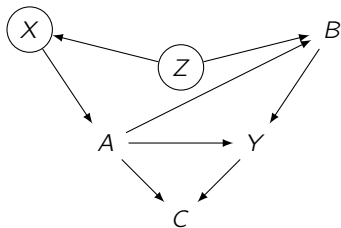
#Load the pyCIPHOD package
from pyciphod.graphs import DirectedAcyclicGraph
from pyciphod.causal_reasoning import back_door_criterion
from pyciphod.causal_reasoning import front_door_criterion
#Define the DAG
g = DirectedAcyclicGraph()
g.add_vertices(["A", "B", "C", "D"])
g.add_directed_edge('B', 'A')
g.add_directed_edge('B', 'C')
g.add_directed_edge('A', 'D')
g.add_directed_edge('D', 'C')
#Check if B satisfies the back-door criterion for (A,C)
bd = back_door_criterion(g, ["A"], ["C"], ["B"])
print(bd)
#Check if D satisfies the front-door criterion for (A,C)
fd = front_door_criterion(g, ["A"], ["C"], ["D"])
print(fd)

```

Consider that in the following causal DAG, only A and Y , and one additional variable can be measured. Which variable would allow the identification of $P(y | do(a))$?

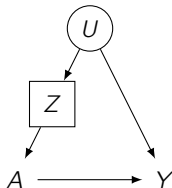


- Consider the following causal DAG. List all sets of variables that satisfy the back-door criterion for $P(y | do(a))$;

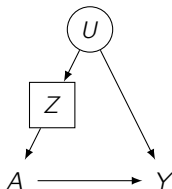


Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

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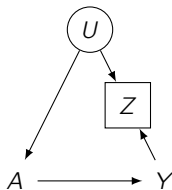


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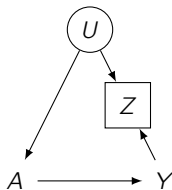


- Z blocks all **non-causal paths** and it is not a descendant of A
 $\implies \{Z\}$ is a good adjustment set.

Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

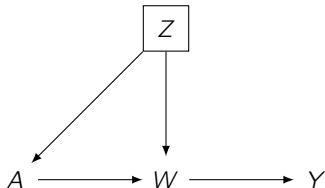


Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

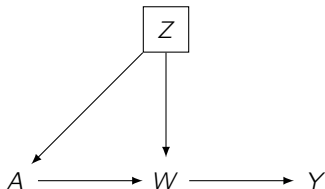


- Z activates a back-door path
 $\implies \{Z\}$ is a bad adjustment set.

Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

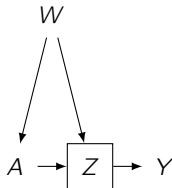


Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

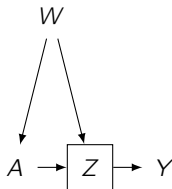


- Z blocks all **non-causal paths** and it is not a descendant of A
 $\implies \{Z\}$ is a good adjustment set.

Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

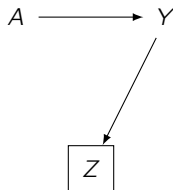


Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

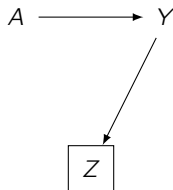


- Z d-separates A from Y
 $\implies \{Z\}$ is a bad adjustment set.

Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

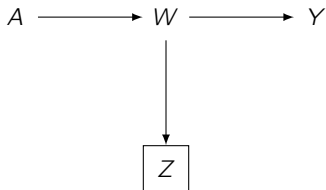


Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

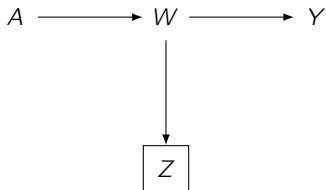


- Selection bias
 $\implies \{Z\}$ is a bad control.

Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

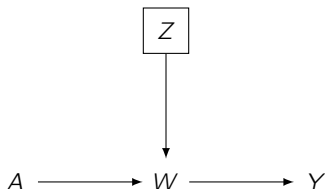


Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?

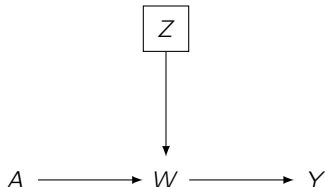


- Z is a descendant of A
 $\implies \{Z\}$ is a bad adjustment set.

Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?



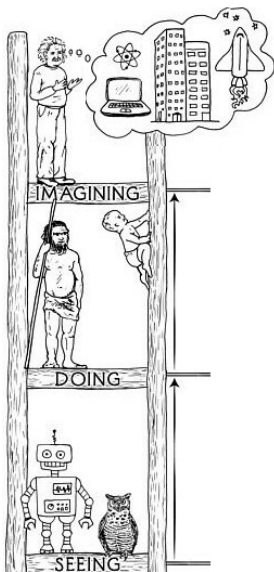
Is $\{Z\}$ a good, bad or neutral adjustment set for $P(y \mid do(a))$?



- Z is a parent of a mediator W
 $\implies \{Z\}$ is a neutral adjustment set but good for optimality.

4

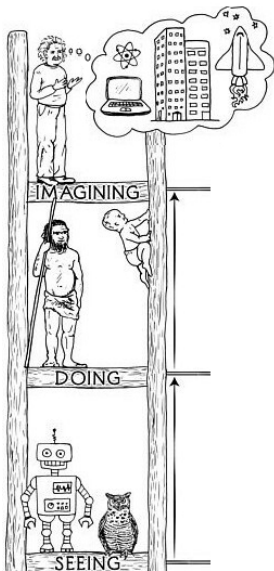
Conclusion



Counterfactuals

Interventions

Associations



Counterfactuals

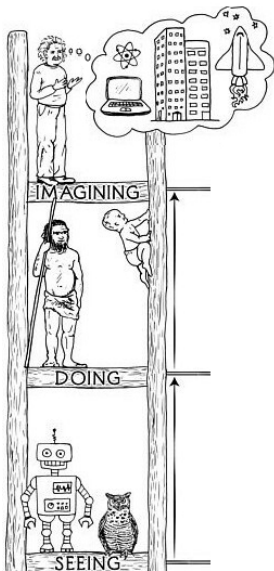
Interventions

Associations

Bayesian network

Causal DAG

Bayesian network



Counterfactuals

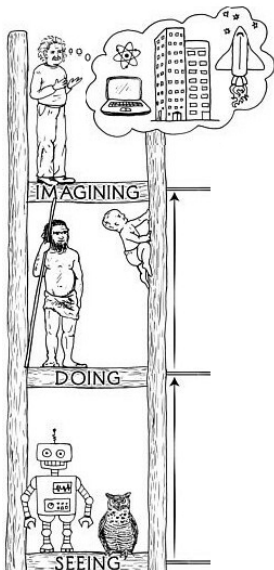
Interventions

Associations

?

Causal DAG

Bayesian network



Counterfactuals

Interventions

Associations

5

References

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THANK YOU!

