

CAUSAL DISCOVERY

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- 3 Noise-based causal discovery
- 4 Practical considerations
- 5 Conclusion

1

PRELIMINARIES

A causal DAG $\mathcal{G} = (\mathbb{V}, \mathbb{E})$ is a directed acyclic graph where

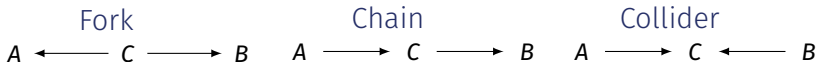
- \mathbb{V} is the set of vertices representing random variables.
- \mathbb{E} is the set of directed edges representing causal relations between these variables.

Markov condition:

$$\forall Y \in \mathbb{V}, Y \perp\!\!\!\perp_{\mathcal{P}} Z \mid \text{Parents}(Y).$$

- $Z : \mathbb{V} \setminus \{\text{Descendants}(Y), \text{Parents}(Y)\}$.
- $\perp\!\!\!\perp_{\mathcal{P}}$: Statistical independence.

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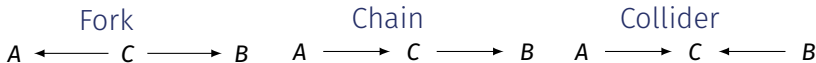
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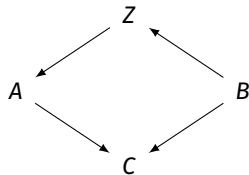
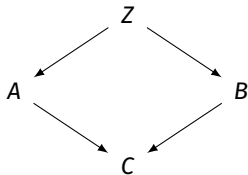
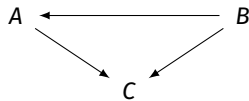
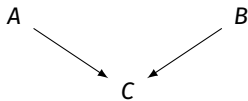
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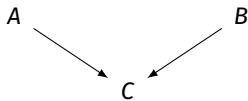
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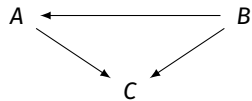
V-structure: collider where the extremities are not adjacent.



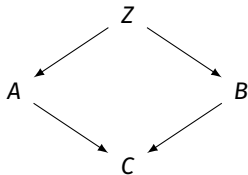
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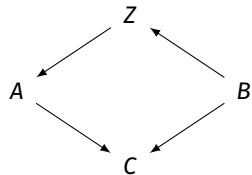
Not v-structure



V-structure



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A path is said to be **blocked** by a set of vertices $\mathbb{Z} \in \mathbb{V}$ if:

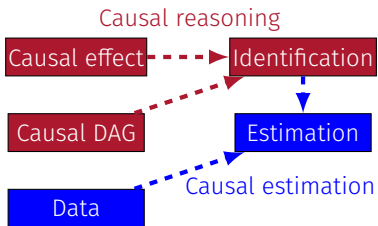
- it contains a chain $A \rightarrow B \rightarrow C$ or a fork $A \leftarrow B \rightarrow C$ and $B \in \mathbb{Z}$; or
- it contains a collider $A \rightarrow B \leftarrow C$ such that no descendant of B is in \mathbb{Z} .

Given disjoint sets $\mathbb{X}, \mathbb{Y}, \mathbb{Z} \subseteq \mathbb{V}$, we say that \mathbb{X} and \mathbb{Y} are **d-separated** by \mathbb{Z} if every path between a vertex in \mathbb{X} and a vertex in \mathbb{Y} is blocked by \mathbb{Z} and we write $\mathbb{X} \perp\!\!\!\perp_{\mathcal{G}} \mathbb{Y} \mid \mathbb{Z}$.

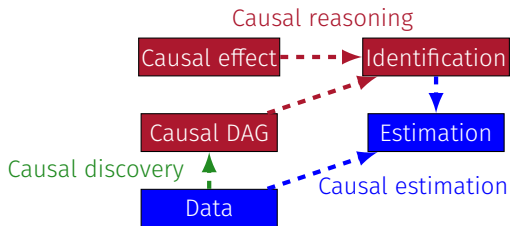
$$\mathbb{X} \perp\!\!\!\perp_{\mathcal{G}} \mathbb{Y} \mid \mathbb{Z} \Rightarrow \mathbb{X} \perp\!\!\!\perp_{\mathcal{P}} \mathbb{Y} \mid \mathbb{Z}$$

but $\mathbb{X} \not\perp\!\!\!\perp_{\mathcal{G}} \mathbb{Y} \mid \mathbb{Z} \not\Rightarrow \mathbb{X} \not\perp\!\!\!\perp_{\mathcal{P}} \mathbb{Y} \mid \mathbb{Z}$

WHAT IF THE CAUSAL DAG IS UNKNOWN?

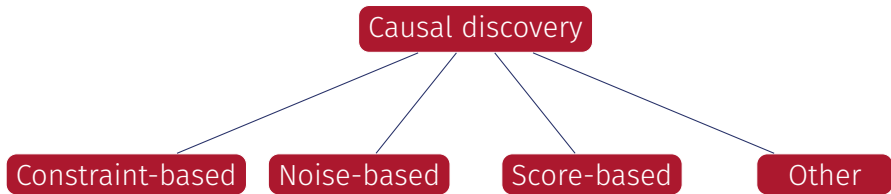


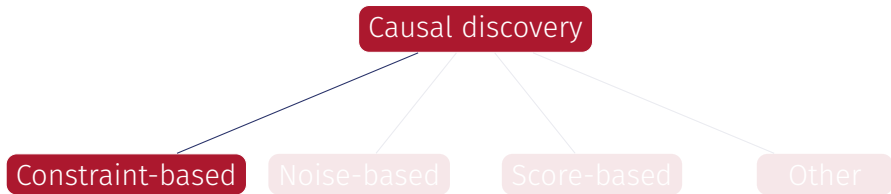
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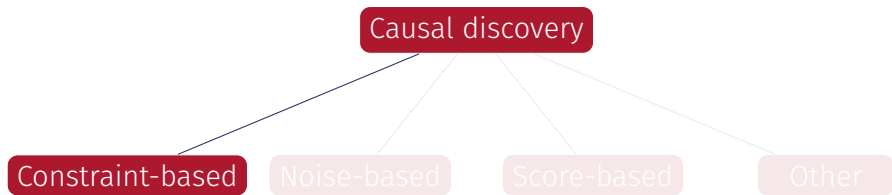


2

CONSTRAINT-BASED CAUSAL DISCOVERY







Constraint-based: run local tests of independence to create constraints on space of possible graphs.

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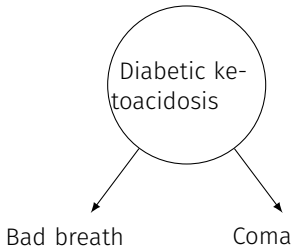
We cannot even construct the skeleton of the graph because

- $\perp\!\!\!\perp_P \not\Rightarrow \perp\!\!\!\perp_G$
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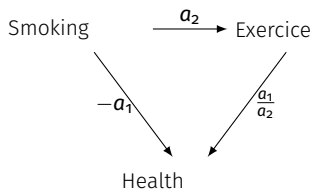
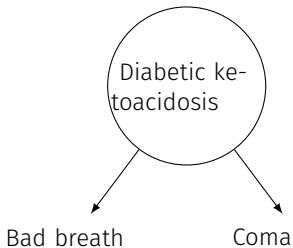
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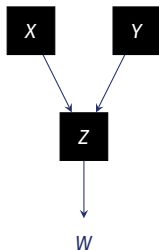


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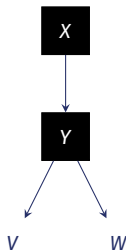
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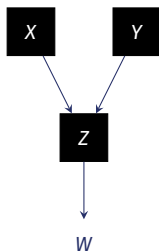
(a)



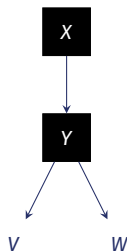
(b)

- (a) $Z = X + Y$:
- (b) $Y = 2X$:

^oExample from [5]



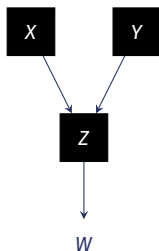
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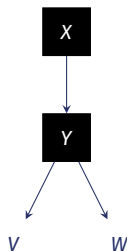
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- (a) $Z = X + Y$: $W \perp\!\!\!\perp_P Z \mid \{X, Y\}$, but $W \not\perp\!\!\!\perp_G Z \mid \{X, Y\}$
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- (a) $Z = X + Y$: $W \perp\!\!\!\perp_P Z \mid \{X, Y\}$, but $W \not\perp\!\!\!\perp_G Z \mid \{X, Y\}$
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Given observational data, is it possible to infer a causal DAG using conditional independencies under the assumptions of faithfulness and causal sufficiency? **In general no!**

Equivalence in terms of conditional independence

$X \rightarrow Y$	$X \leftarrow Y$	$X \rightarrow Z \leftarrow Y$
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- All equivalent graphs can be represented by a completed partially DAG (CPDAG)
- This CPDAG is called the representative of the Markov equivalence class

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If $P(\mathbb{V})$ is faithful to some causal DAG \mathcal{G} with vertex \mathbb{V} then:

- *For $X, Y \in \mathbb{V}$, X and Y are adjacent iff $\forall S \subseteq \mathbb{V} \setminus \{X, Y\}$, $X \not\perp\!\!\!\perp_P Y \mid S$;*

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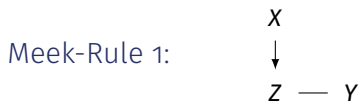
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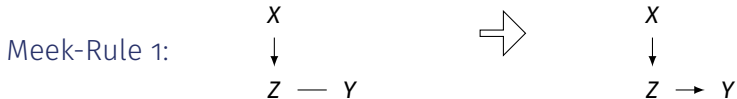
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- Point 1 can be used to discover the skeleton of \mathcal{G} from $P(\mathbb{V})$;
- Given the skeleton of \mathcal{G} , point 2 can be used to find all v-structures.

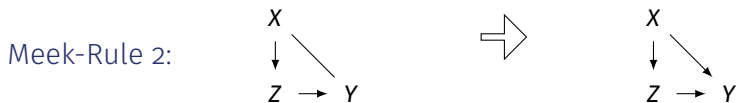
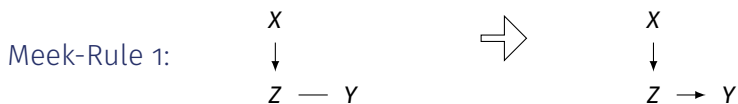
Suppose we already found the skeleton and all v-structures:



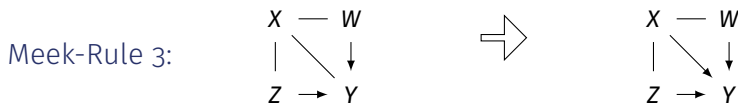
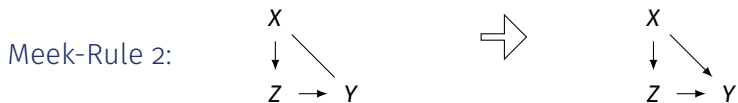
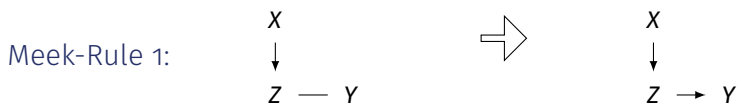
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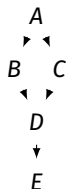
Theorem ([11])

Assume the distribution P is compatible and faithful to some causal DAG \mathcal{G} and assume that we are given perfect conditional independence information about all pairs of variables. The PC algorithm returns the CPDAG of \mathcal{G} .

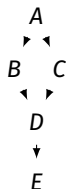
Pruning unnecessary edges in optimal way:

- use a sequential conditioning strategy, where the size of the conditioning set increases progressively from 1 to $p-2$
- the conditioned set is the subset of the set of variables adjacent to tested variables
- storing the separation sets, which can later be used for orienting v-structures and other triplets

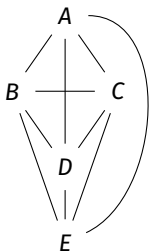
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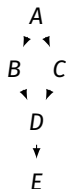


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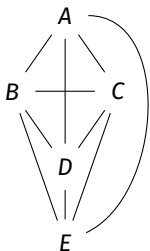


card = 0

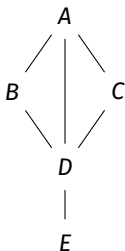
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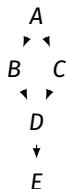


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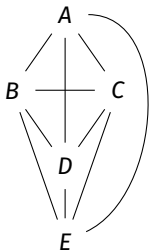


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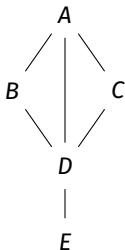
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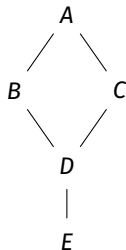
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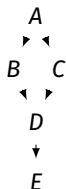


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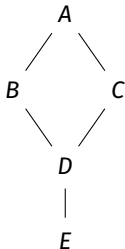


card = 2

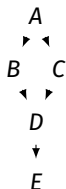
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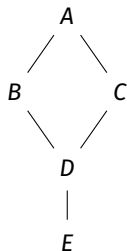
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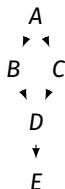


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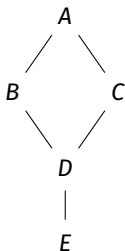


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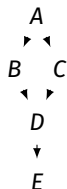


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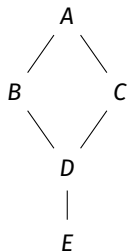


- Finding V-structures
 - ▶ $B \perp\!\!\!\perp_p C \mid A$
 $\implies B \rightarrow D \leftarrow C$

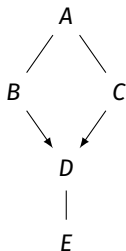
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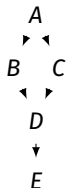
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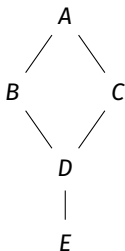
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 - ▶ $B \perp\!\!\!\perp_p C \mid A$
 $\implies B \rightarrow D \leftarrow C$



- Suppose the causal DAG on the right
- Input: Observational data
- Output: CPDAG
- Assumptions: causal sufficiency, faithfulness

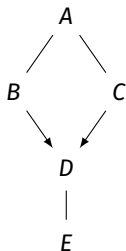


Orientation:

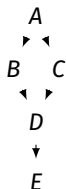


- Finding V-structures
 - ▶ $B \perp\!\!\!\perp_p C \mid A$
 $\implies B \rightarrow D \leftarrow C$

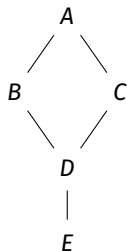
- Meek-Rule 1



- Suppose the causal DAG on the right
- Input: Observational data
- Output: CPDAG
- Assumptions: causal sufficiency, faithfulness

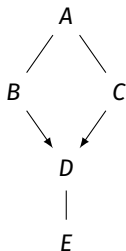


Orientation:

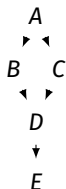


- Finding V-structures
 - ▶ $B \perp\!\!\!\perp_p C \mid A$
 $\implies B \rightarrow D \leftarrow C$

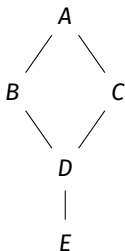
- Meek-Rule 1
 - ▶ $B \rightarrow D \& D - E$
 $\implies D \rightarrow E$



- Suppose the causal DAG on the right
- Input: Observational data
- Output: CPDAG
- Assumptions: causal sufficiency, faithfulness

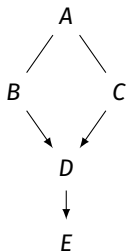


Orientation:



- Finding V-structures
 - ▶ $B \perp\!\!\!\perp_p C \mid A$
 $\implies B \rightarrow D \leftarrow C$

- Meek-Rule 1
 - ▶ $B \rightarrow D \ \& \ D - E$
 $\implies D \rightarrow E$

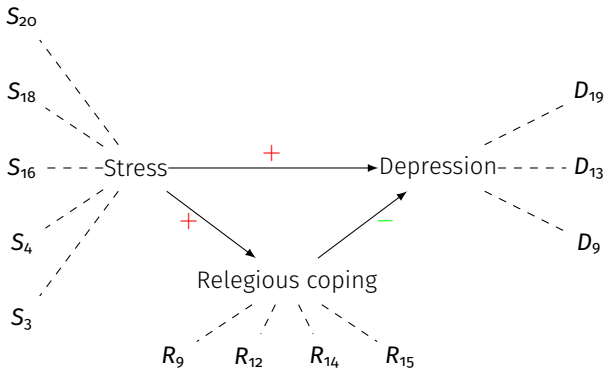


The PC algorithm can effectively incorporate background knowledge in the form of:

- Forbidden edges
- Required edges
- Forbidden orientations
- Required orientations

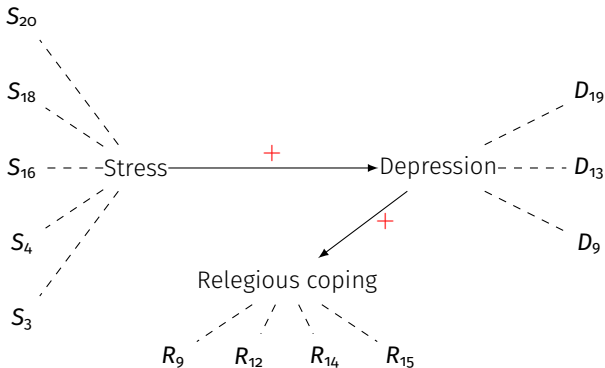
MSW students ($N = 127$); 61 item survey (Likert Scale)

Specified graph



MSW students ($N = 127$); 61 item survey (Likert Scale)

Inferred graph (assuming stress is temporally prior)



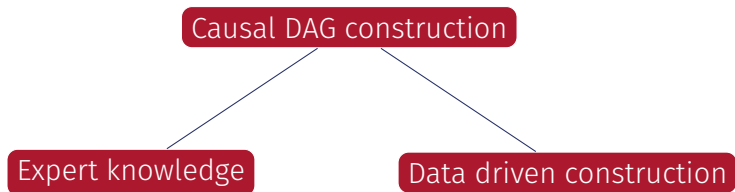
Main idea: Assign each variable X to an ordered tier (e.g., its measurement period).

Tiered background information can be used in the PC algorithm in the following way:

- Skeleton phase: test $X \perp\!\!\!\perp Y \mid \mathcal{S}$ only if \mathcal{S} is not later than both X and Y
- Orientation phase: if X is temporally prior to Y orient $X \rightarrow Y$

Temporal PC(tPC) [11, 8]: The output of the tPC is more informative than CPDAG, as temporal knowledge can orient edges that remain undirected in the CPDAG.

Aim: Life course study on etiology of depression and heart disease in early old age



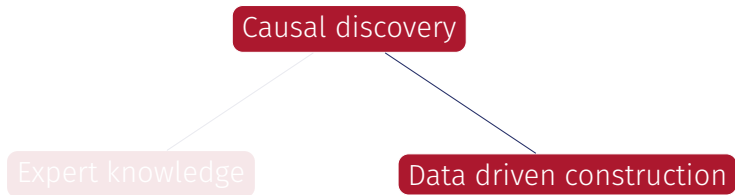
LIFE COURSE STUDY: DEPRESSION AND HEART DISEASE ETIOLOGY IN THE METROPOLITAN COHORT

Aim: Life course study on etiology of depression and heart disease in early old age



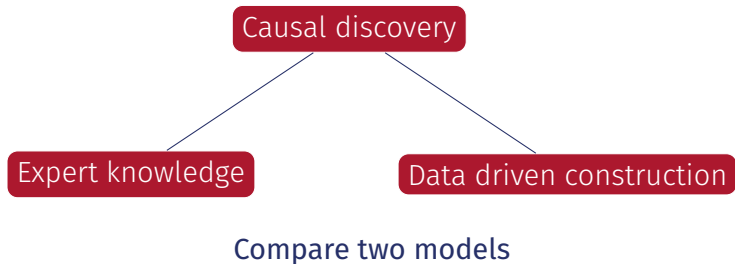
Two experts build a causal DAG (individual + consensus)

Aim: Life course study on etiology of depression and heart disease in early old age

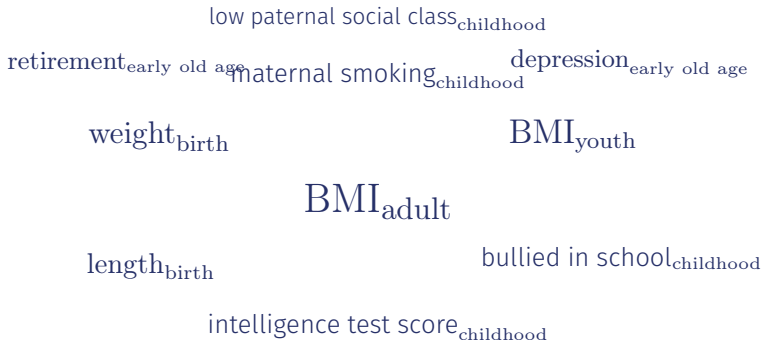


Apply temporal PC algorithm on data

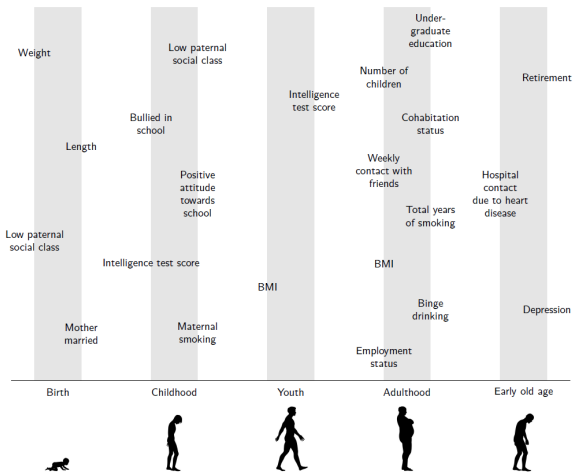
Aim: Life course study on etiology of depression and heart disease in early old age



LIFE COURSE STUDY: DEPRESSION AND HEART DISEASE ETIOLOGY IN THE METROPOLITAN COHORT.

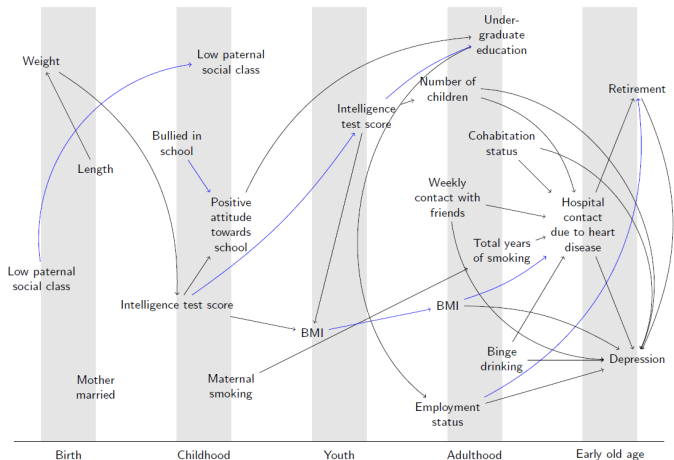


LIFE COURSE STUDY: DEPRESSION AND HEART DISEASE ETIOLOGY IN THE METROPOLITAN COHORT.

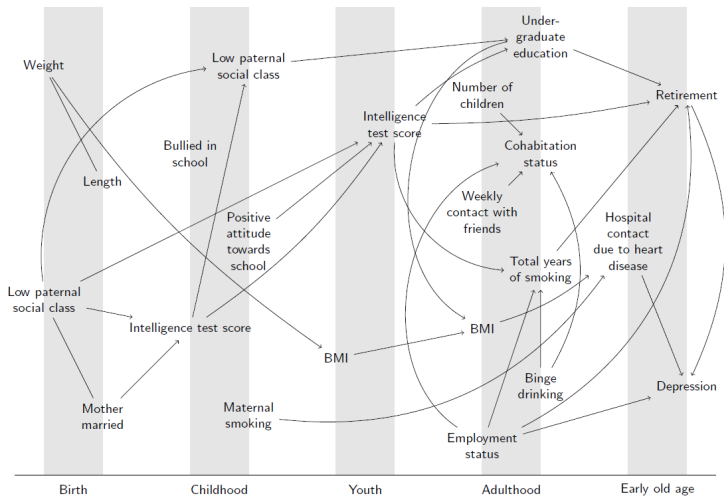


Petersen, Ekstrøm, Spirtes & Osler (2023). Constructing causal life course models: Comparative study of data-driven and theory-driven approaches. *American Journal of Epidemiology*

METROPOLIT RESULTS: EXPERT MODEL



METROPOLIT RESULTS: CAUSAL DISCOVERY MODEL



Shared adjacencies: no orientation disagreement, except one non-oriented edge.

		Experts	
		Adjacency	Non-adjacency
Causal discovery	Adjacency	10	20
	Non-adjacency	20	181

- **Shared adjacencies:** no orientation disagreement
- **Experts high confidence edges:** 6 out of 7 found by causal discovery algorithm
- 'Extra' 20 edges found by TPC
 - ▶ Low plausibility 3
 - ▶ Moderate plausibility 6
 - ▶ High plausibility 11

Consider a causal DAG \mathcal{G} and a causal effect $P(y \mid do(x))$. A set of variables \mathbb{Z} satisfies the **back-door criterion** if:

- no vertex in \mathbb{Z} is a descendant of X ;
- \mathbb{Z} **blocks** every non causal path from X to Y .

Works for DAGs, but we have CPDAG?

J. Pearl, M. Glymour, and N. P. Jewell. *Causation Inference In Statistics: A Primer*. Wiley, 2016.

Causal path: a directed path from X to Y , where all arrowheads point away from X . e.g. $X \rightarrow Z \rightarrow Y$

Possible causal path: a path from X to Y , such that there is no arrow pointing towards X e.g. $X - Z \rightarrow Y$

Non-causal path: a path from X to Y that is not possible causal, e.g. $X - Z \leftarrow Y$, $X \leftarrow Z - Y$

Possible descendants

If there is a possibly causal path from X to Y , then

- Y a possible descendant of X .

Consider a CPDAG \mathcal{G} and a causal effect $P(y \mid \text{do}(x))$. A set of variables \mathbb{Z} satisfies the **generalized back-door criterion** if:

- \mathbb{Z} does not contain **possible** descendants of X in \mathcal{G} ;
- \mathbb{Z} **blocks** all non-causal paths from X to Y in \mathcal{G}

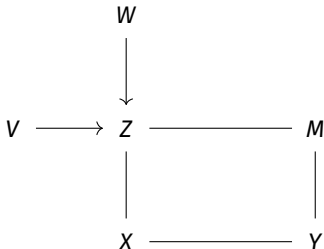
Consider a CPDAG \mathcal{G} and a causal effect $P(y \mid \text{do}(x))$. A set of variables \mathbb{Z} satisfies the **generalized back-door criterion** if:

- for any possible causal path between X and Y , the edge adjacent to X on the path is oriented;
- \mathbb{Z} does not contain **possible** descendants of X in \mathcal{G} ;
- \mathbb{Z} **blocks** all non-causal paths from X to Y in \mathcal{G}

Consider a CPDAG \mathcal{G} and a causal effect $P(y \mid \text{do}(x))$. A set of variables \mathbb{Z} satisfies the **generalized back-door criterion** if:

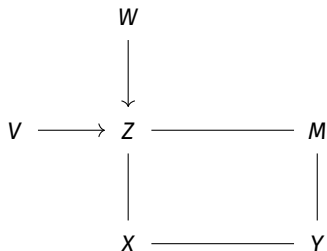
- for any possible causal path between X and Y , the edge adjacent to X on the path is oriented;
- \mathbb{Z} does not contain **possible** descendants of X in \mathcal{G} ;
- \mathbb{Z} **blocks** all non-causal paths from X to Y in \mathcal{G}

$$P(y \mid \text{do}(x)) = \sum_z P(y \mid x, z)P(z).$$



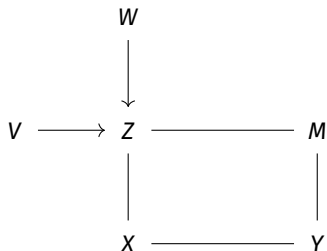
Is it a CPDAG?

Is the generalized back-door criterion satisfied?



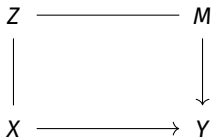
Is it a CPDAG? **No!**

Is the generalized back-door criterion satisfied?



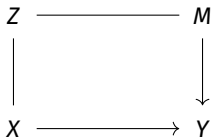
Is it a CPDAG? **No!**

Is the generalized back-door criterion satisfied? **No!**



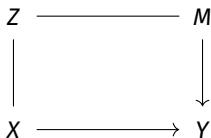
Is it a CPDAG?

Is the generalized back-door criterion satisfied?



Is it a CPDAG? **Yes!**

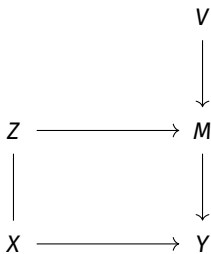
Is the generalized back-door criterion satisfied?



Is it a CPDAG? **Yes!**

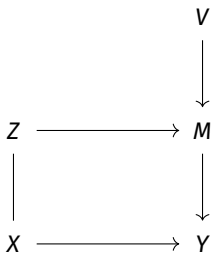
Is the generalized back-door criterion satisfied? **No!**

$X - Z - M \rightarrow Y$ is a possibly causal path and the first edge on the path is not oriented.



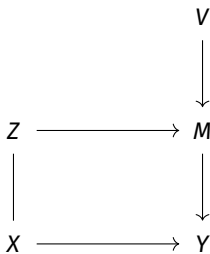
Is it a CPDAG?

Is the generalized back-door criterion satisfied?



Is it a CPDAG? **Yes!**

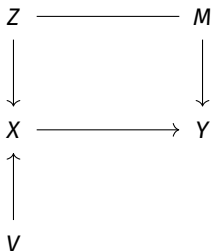
Is the generalized back-door criterion satisfied?



Is it a CPDAG? **Yes!**

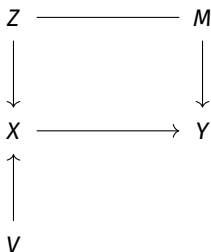
Is the generalized back-door criterion satisfied? **No!**

$X - Z - M \rightarrow Y$ is a possibly causal path and the first edge on the path is not oriented.



Is it a CPDAG?

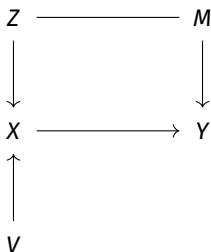
Is the generalization of the back-door criterion satisfied?



Is it a CPDAG? **Yes!**

Is the generalization of the back-door criterion satisfied?

EXAMPLE 4

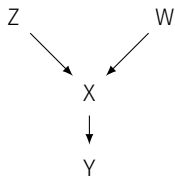


Is it a CPDAG? **Yes!**

Is the generalization of the back-door criterion satisfied? **Yes!**

$\{Z\}$, $\{M\}$, $\{Z, M\}$ satisfy the criterion.

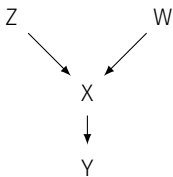
BEYOND CAUSAL SUFFICIENCY (1/2)



Y-structure

$$\begin{array}{l}
 Z \perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p W \mid X \\
 Y \not\perp\!\!\!\perp_p Z \\
 Y \perp\!\!\!\perp_p Z \mid X \\
 Y \not\perp\!\!\!\perp_p W \\
 Y \perp\!\!\!\perp_p W \mid X
 \end{array}$$

BEYOND CAUSAL SUFFICIENCY (1/2)

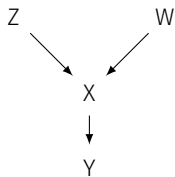


Y-structure

$$\begin{array}{l}
 Z \perp\!\!\!\perp_P W \\
 Z \not\perp\!\!\!\perp_P W \mid X \\
 Y \not\perp\!\!\!\perp_P Z \\
 Y \perp\!\!\!\perp_P Z \mid X \\
 Y \not\perp\!\!\!\perp_P W \\
 Y \perp\!\!\!\perp_P W \mid X
 \end{array}$$

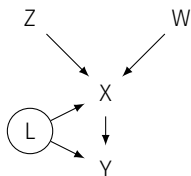
Can we have a hidden confounder between X and Y?

BEYOND CAUSAL SUFFICIENCY (1/2)



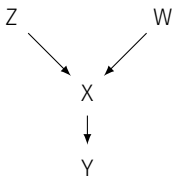
Y-structure

$$\begin{array}{l}
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 Z \not\perp\!\!\!\perp_p W \mid X \\
 Y \not\perp\!\!\!\perp_p Z \\
 Y \perp\!\!\!\perp_p Z \mid X \\
 Y \not\perp\!\!\!\perp_p W \\
 Y \perp\!\!\!\perp_p W \mid X
 \end{array}$$



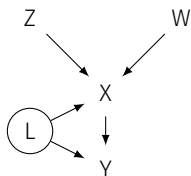
$$\begin{array}{l}
 Z \perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p W \mid X \\
 Y \not\perp\!\!\!\perp_p Z \\
 Y \not\perp\!\!\!\perp_p Z \mid X \\
 Y \not\perp\!\!\!\perp_p W \\
 Y \not\perp\!\!\!\perp_p W \mid X
 \end{array}$$

BEYOND CAUSAL SUFFICIENCY (1/2)



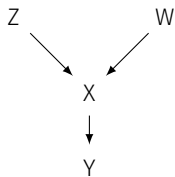
Y-structure

$$\begin{array}{l}
 Z \perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p W \mid X \\
 Y \not\perp\!\!\!\perp_p Z \\
 Y \perp\!\!\!\perp_p Z \mid X \\
 Y \not\perp\!\!\!\perp_p W \\
 Y \perp\!\!\!\perp_p W \mid X
 \end{array}$$



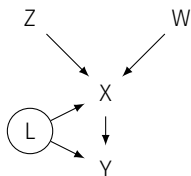
$$\begin{array}{l}
 Z \perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p W \mid X \\
 Y \not\perp\!\!\!\perp_p Z \\
 Y \not\perp\!\!\!\perp_p Z \mid X \\
 Y \not\perp\!\!\!\perp_p W \\
 Y \not\perp\!\!\!\perp_p W \mid X
 \end{array}$$

BEYOND CAUSAL SUFFICIENCY (1/2)



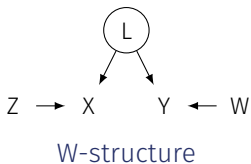
Y-structure

$$\begin{array}{l}
 Z \perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p W \mid X \\
 Y \not\perp\!\!\!\perp_p Z \\
 Y \perp\!\!\!\perp_p Z \mid X \\
 Y \not\perp\!\!\!\perp_p W \\
 Y \perp\!\!\!\perp_p W \mid X
 \end{array}$$

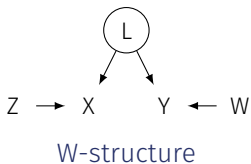


$$\begin{array}{l}
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 Z \not\perp\!\!\!\perp_p W \mid X \\
 Y \not\perp\!\!\!\perp_p Z \\
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 Y \not\perp\!\!\!\perp_p W \\
 Y \not\perp\!\!\!\perp_p W \mid X
 \end{array}$$

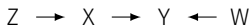
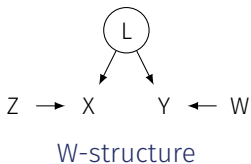
Pattern of independence can rule out hidden confounding.



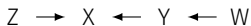
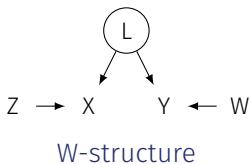
$$\begin{array}{l}
 Z \not\perp\!\!\!\perp_p X \\
 X \not\perp\!\!\!\perp_p Y \\
 Y \not\perp\!\!\!\perp_p W \\
 Z \perp\!\!\!\perp_p W \\
 Z \perp\!\!\!\perp_p Y \\
 X \perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p Y \mid X \\
 X \not\perp\!\!\!\perp_p W \mid Y
 \end{array}$$



- $Z \not\perp\!\!\!\perp_p X$
- $X \not\perp\!\!\!\perp_p Y$
- $Y \not\perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p Y$
- $X \perp\!\!\!\perp_p W$
- $Z \not\perp\!\!\!\perp_p Y \mid X$
- $X \not\perp\!\!\!\perp_p W \mid Y$
- $Z \not\perp\!\!\!\perp_p X$
- $X \not\perp\!\!\!\perp_p Y$
- $Y \not\perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p W$
- $Z \not\perp\!\!\!\perp_p Y$
- $X \perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p Y \mid X$
- $X \not\perp\!\!\!\perp_p W \mid Y$

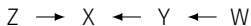
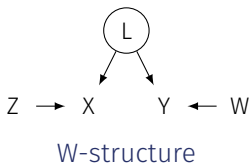


- $Z \not\perp\!\!\!\perp_p X$
- $X \not\perp\!\!\!\perp_p Y$
- $Y \not\perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p Y$
- $X \perp\!\!\!\perp_p W$
- $Z \not\perp\!\!\!\perp_p Y \mid X$
- $X \not\perp\!\!\!\perp_p W \mid Y$
- $Z \not\perp\!\!\!\perp_p X$
- $X \not\perp\!\!\!\perp_p Y$
- $Y \not\perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p W$
- $Z \not\perp\!\!\!\perp_p Y$
- $X \perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p Y \mid X$
- $X \not\perp\!\!\!\perp_p W \mid Y$



- $Z \not\perp\!\!\!\perp_p X$
- $X \not\perp\!\!\!\perp_p Y$
- $Y \not\perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p Y$
- $X \perp\!\!\!\perp_p W$
- $Z \not\perp\!\!\!\perp_p Y \mid X$
- $X \not\perp\!\!\!\perp_p W \mid Y$
- $Z \not\perp\!\!\!\perp_p X$
- $X \not\perp\!\!\!\perp_p Y$
- $Y \not\perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p W$
- $Z \perp\!\!\!\perp_p Y$
- $X \not\perp\!\!\!\perp_p W$
- $Z \not\perp\!\!\!\perp_p Y \mid X$
- $X \perp\!\!\!\perp_p W \mid Y$

BEYOND CAUSAL SUFFICIENCY (2/2)



$$\begin{array}{l}
 Z \not\perp\!\!\!\perp_p X \\
 X \not\perp\!\!\!\perp_p Y \\
 Y \not\perp\!\!\!\perp_p W \\
 Z \perp\!\!\!\perp_p W \\
 Z \perp\!\!\!\perp_p Y \\
 X \perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p Y \mid X \\
 X \not\perp\!\!\!\perp_p W \mid Y \\
 \\
 Z \not\perp\!\!\!\perp_p X \\
 X \not\perp\!\!\!\perp_p Y \\
 Y \not\perp\!\!\!\perp_p W \\
 Z \perp\!\!\!\perp_p W \\
 Z \perp\!\!\!\perp_p Y \\
 X \not\perp\!\!\!\perp_p W \\
 Z \not\perp\!\!\!\perp_p Y \mid X \\
 X \perp\!\!\!\perp_p W \mid Y
 \end{array}$$

Pattern of independence can suggest hidden confounding.

The FCI algorithm extends the PC algorithm to accommodate hidden confounders:

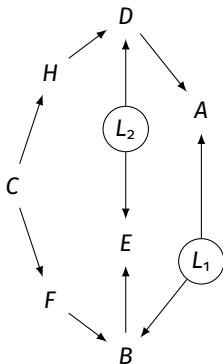
The FCI algorithm extends the PC algorithm to accommodate hidden confounders:

- Skeleton construction is much more complicated;
- Orientation is done using 10 different rules.

The FCI algorithm extends the PC algorithm to accommodate hidden confounders:

- Skeleton construction is much more complicated;
- Orientation is done using 10 different rules.

The FCI algorithm in action:

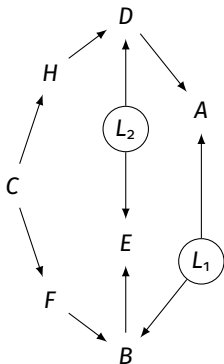


True graph

The FCI algorithm extends the PC algorithm to accommodate hidden confounders:

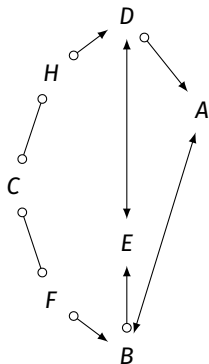
- Skeleton construction is much more complicated;
- Orientation is done using 10 different rules.

The FCI algorithm in action:



True graph

Causal discovery



Inferred graph

Constraint-based causal discovery

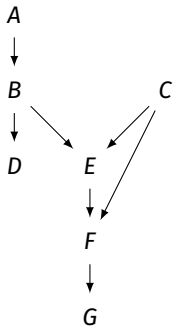
Pros:

- Non-parametric (in practice, it depends on the selected independence test)
- Intuitive

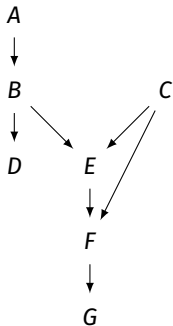
Cons:

- Recover a partially oriented graph
- The faithfulness assumption is not always accepted

What is the CPDAG of the following causal DAG?

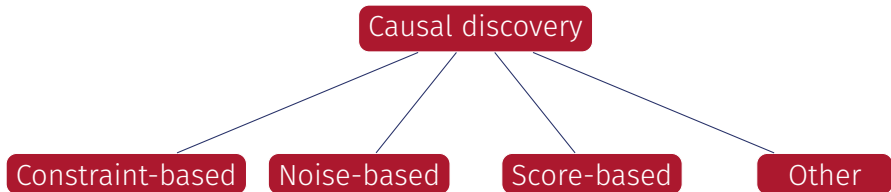


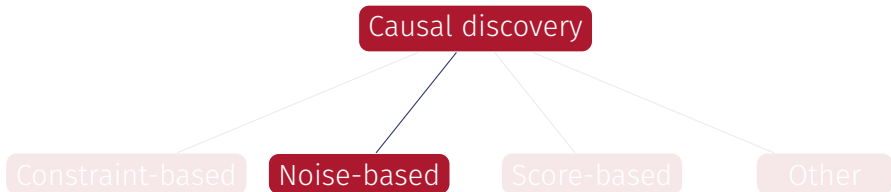
What will be the output of PC if $A = B$?

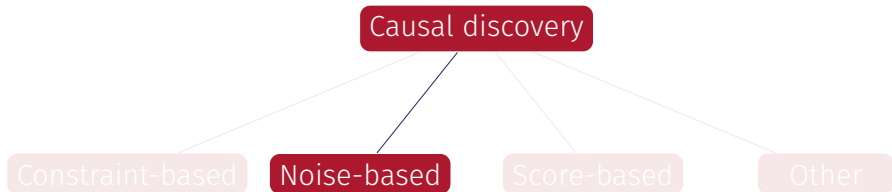


3

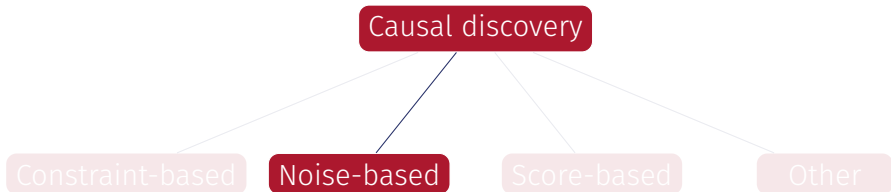
NOISE-BASED CAUSAL DISCOVERY







Noise-based: find footprints in the noise that imply causal asymmetry.



Noise-based: find footprints in the noise that imply causal asymmetry.

Also known as semi-parametric-based or functional-based.

$$\text{Suppose } \begin{cases} X := \xi_x \\ Y := 2X + \xi_y \end{cases}$$

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Given $P(X, Y)$, one can detect $X - Y$ but what about orientation?

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$$Y := 2X + \xi_y ?$$

or

$$X := \frac{Y}{2} + \hat{\xi}_x ?$$

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Assume that the noise follow a uniform distribution on $\{-1, 0, 1\}$

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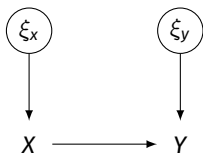
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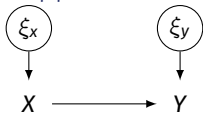
X	Y	$\xi_y = Y - 2X$	$\hat{\xi}_x = X - Y/2$
1	2	$0 \in \{-1, 0, 1\}$	$0 \in \{-1, 0, 1\}$
3	6	$0 \in \{-1, 0, 1\}$	$0 \in \{-1, 0, 1\}$
4	9	$1 \in \{-1, 0, 1\}$	$-0.5 \notin \{-1, 0, 1\}$



$$M_1 : \begin{cases} X := f_x(\xi_x) \\ Y := f_y(X, \xi_y) \end{cases}$$

- $X \perp\!\!\!\perp_G \xi_y$
- $Y \not\perp\!\!\!\perp_G \xi_x$

Suppose

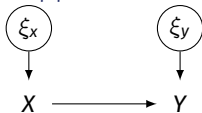


$$X \sim N(0, 1)$$

$$\xi_y \sim N(0, 1)$$

$$Y := 2X + \xi_y$$

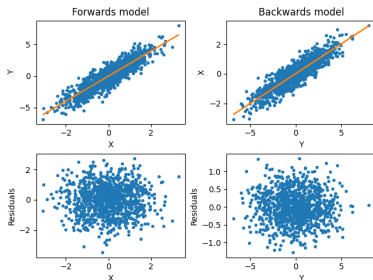
Suppose



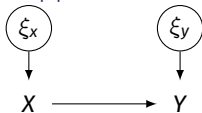
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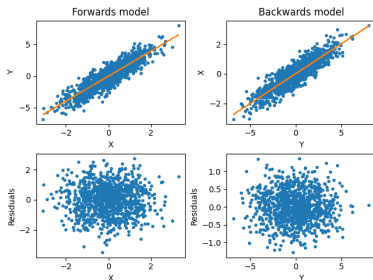
$$\xi_y \sim N(0, 1)$$

$$Y := 2X + \xi_y$$

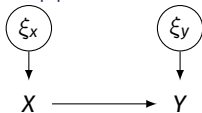
$$X \sim U(0, 1)$$

$$\xi_y \sim U(0, 1)$$

$$Y := 2X + \xi_y$$



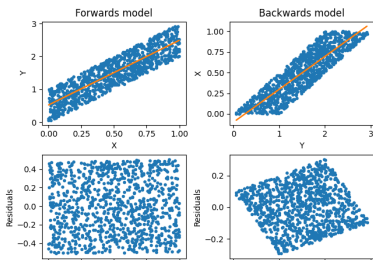
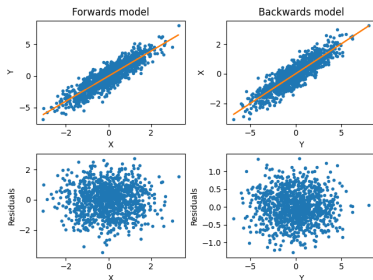
Suppose



$$X \sim N(0, 1)$$

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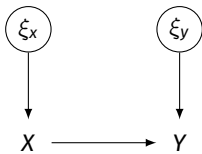
$$Y := 2X + \xi_y$$

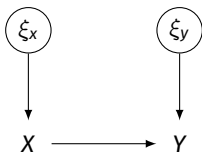


$$X \sim U(0, 1)$$

$$\xi_y \sim U(0, 1)$$

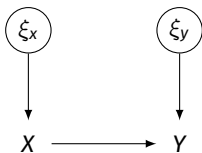
$$Y := 2X + \xi_y$$





True model:

$$M_1 : \begin{cases} X := \xi_x \\ Y := aX + \xi_y \end{cases} \quad \blacksquare \quad X \perp\!\!\!\perp_P \xi_y$$

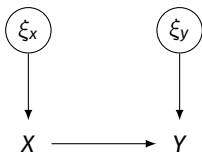


True model:

$$M_1 : \begin{cases} X := \xi_x \\ Y := aX + \xi_y \end{cases} \quad \blacksquare X \perp\!\!\!\perp_P \xi_y$$

Backwards model:

$$M_2 : \begin{cases} Y := \hat{\xi}_y \\ X := bY + \hat{\xi}_x \end{cases} \quad \blacksquare Y \perp\!\!\!\perp_P \hat{\xi}_x?$$



True model:

$$M_1 : \begin{cases} X := \xi_x \\ Y := aX + \xi_y \end{cases} \quad \blacksquare X \perp\!\!\!\perp_P \xi_y$$

Backwards model:

$$M_2 : \begin{cases} Y := \hat{\xi}_y \\ X := bY + \hat{\xi}_x \end{cases} \quad \blacksquare Y \perp\!\!\!\perp_P \hat{\xi}_x?$$

$$\begin{aligned} \hat{\xi}_x &= X - bY \\ &= X - b(aX + \xi_y) \\ &= (1 - ba)X - b\xi_y \end{aligned}$$

$$Y = aX + \xi_y$$

$$\hat{\xi}_x = (1 - ba)X - b\xi_y$$

When $Y \perp\!\!\!\perp_P \hat{\xi}_x$?

$$Y = aX + \xi_y$$

$$\hat{\xi}_x = (1 - ba)X - b\xi_y$$

When $Y \perp\!\!\!\perp_P \hat{\xi}_x$?

Theorem (Darmois-Skitovich)

Let X_1, \dots, X_n be independent, non degenerate random variables. If for two linear combinations:

$$l_1 = a_1X_1 + \dots + a_nX_n$$

$$l_2 = b_1X_1 + \dots + b_nX_n$$

are independent, then each X_i is normally distributed.

Theorem

Assume that $P(X, Y)$ admits the linear model

$$Y := aX + \xi_y, \quad X \perp\!\!\!\perp_P \xi_y,$$

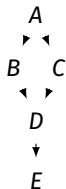
with continuous random variables X , ξ_y , and Y . Then there exists $b \in \mathbb{R}$ and a random variable $\hat{\xi}_x$ such that

$$X := bY + \hat{\xi}_x, \quad Y \perp\!\!\!\perp_P \hat{\xi}_x,$$

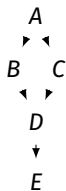
iff ξ_y and X are Gaussian.

Similar result for the multivariate case

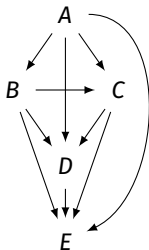
- Suppose the causal DAG on the right
- Input: Observational data
- Output: Causal DAG
- Assumptions: causal sufficiency, **minimality**, linearity, non-gaussianity



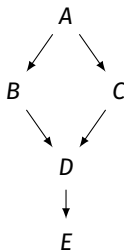
- Suppose the causal DAG on the right
- Input: Observational data
- Output: Causal DAG
- Assumptions: causal sufficiency, **minimality**, linearity, non-gaussianity



Causal order:



Pruning:



Young and middle-aged adults ($N = 2,060$); self-administered questionnaire for TV time

Specified graphs

TV time \longleftrightarrow BMI

TV time \longleftrightarrow Waist circumference

Young and middle-aged adults ($N = 2,060$); self-administered questionnaire for TV time

Inferred graphs

TV time \longrightarrow BMI

TV time \longrightarrow Waist circumference

- LiNGAM with hidden confounding
- Non-linear additive noise models:

$$Y = f(X) + \xi, \quad \xi \perp\!\!\!\perp X.$$

- Post non-linear additive noise models:

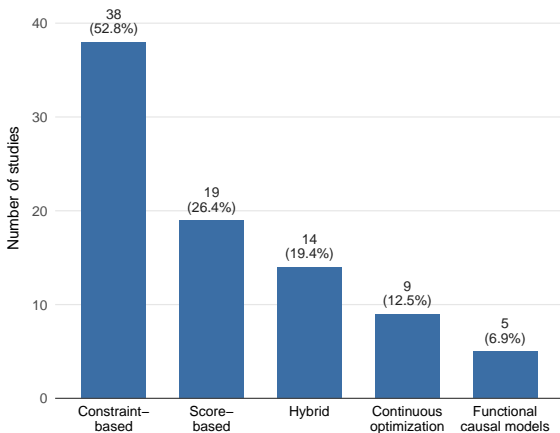
$$Y = g(f(X) + \xi), \quad \xi \perp\!\!\!\perp X,$$

Pros:

- Recover the complete causal DAG

Cons:

- Semi-parametric



¹Liu, Zuting, et al. "Causal Discovery in Observational Medical Research: Scoping Review." JMIR Medical Informatics 14 (2026): e82499.

4

PRACTICAL CONSIDERATIONS

What are the downstream tasks of causal discovery?

What are the downstream tasks of causal discovery?

- Understanding
- Identifying and estimating causal effects

Causal DAG \mathcal{G} , dataset \mathbf{D} , $\beta_{\mathcal{G}}$ is the causal parameter of interest, then we have:

$$\mathbb{P}(\beta_{\mathcal{G}} \notin CI_{\mathcal{G}}(\alpha, \mathbf{D})) \leq \alpha$$

What happens if I use the same data for the causal discovery and estimation?

Causal DAG $\hat{\mathcal{G}}$ estimated from dataset \mathbf{D} , dataset \mathbf{D} , $\beta_{\mathcal{G}}$ is the causal parameter of interest,

Causal DAG \mathcal{G} , dataset D , $\beta_{\mathcal{G}}$ is the causal parameter of interest, then we have:

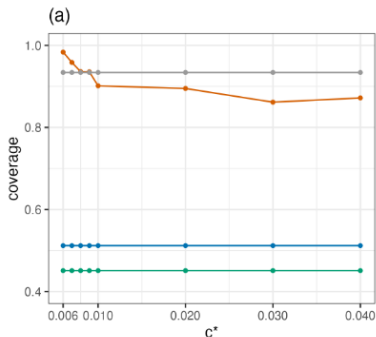
$$\mathbb{P}(\beta_{\mathcal{G}} \notin CI_{\mathcal{G}}(\alpha, D)) \leq \alpha$$

What happens if I use the same data for the causal discovery and estimation?

Causal DAG $\hat{\mathcal{G}}$ estimated from dataset D , dataset D , $\beta_{\mathcal{G}}$ is the causal parameter of interest,

~~$$\mathbb{P}(\beta_{\mathcal{G}} \notin CI_{\hat{\mathcal{G}}}(\alpha, D)) \leq \alpha$$~~

Simulation experiment with tPC algorithm from [1]



Oracle

tPC + solution to double dipping

tPC, $\alpha = 0.01$

tPC, $\alpha = 0.05$

- Split data into two datasets, one for causal discovery and one for estimation
- Resampling method [1]
- Noisy Causal Discovery [3]

To be specified:

- The introduced implementation of PC is order dependent, however there exists order independent implementation introduced by [2]
- A conditional independence measure and test (constraint-based)
- An independence measure and tests (noise-based)
- A significance level in the statistical tests (constraint-based and noise-based)
- **Optional:** Existing expert knowledge (temporal ordering, forbidden orientations,...)

USEFULNESS OF CAUSAL DISCOVERY WHEN ASSUMPTIONS ARE VIOLATED

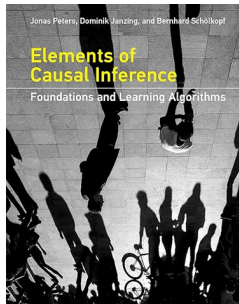
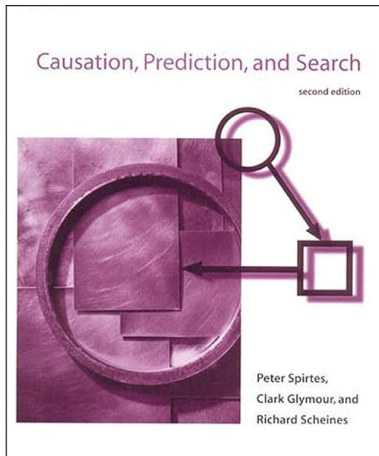
If assumptions are violated, then most causal discovery methods would give a Bayesian network
⇒ this Bayesian network could be used for the selection of the variables for the prediction task.

5

CONCLUSION

- In general, a causal DAG cannot be discovered from observational data alone.
- However, it can be discovered under certain untestable assumptions.
- If you can construct the causal DAG manually based on domain knowledge, then avoid using causal discovery methods (except for prediction).
- Causal discovery is useful only when the causal DAG is unknown and needs to be inferred from data.

- "Review of causal discovery methods based on graphical models" by Clark Glymour, Kun Zhang, and Peter Spirtes, 2019
- "Causal discovery algorithms: A practical guide" by Daniel Malinsky and David Danks, 2018
- "A practical guide to causal discovery with cohort data.", Andrews, Ryan M., Ronja Foraita, Vanessa Didelez, and Janine Witte, 2021.



6

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MERCI POUR VOTRE ATTENTION

